

GEMÜ Q50 eSyStep

Open / Close (Code AE, A5, A6)

Motorized pinch valve

EN

Operating instructions



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1 General information

1.1 Information

- The descriptions and instructions apply to the standard versions. For special versions not described in this document the basic information contained herein applies in combination with any additional special documentation.
- Correct installation, operation, maintenance and repair work ensure faultless operation of the product.
- Should there be any doubts or misunderstandings, the German version is the authoritative document.
- Contact us at the address on the last page for staff training information.

1.2 Symbols used

The following symbols are used in this document:

Symbol	Meaning
●	Tasks to be performed
►	Response(s) to tasks
–	Lists

1.3 LED symbols

The following LED symbols are used in the documentation:

Symbol	LED conditions
○	Off
●	Lit (on)
⦿	Flashing

1.4 Definition of terms

Working medium

The medium that flows through the tube.

1.5 Warning notes

Wherever possible, warning notes are organized according to the following scheme:

SIGNAL WORD	
Possible symbol for the specific danger	Type and source of the danger ►Possible consequences in case of non-compliance ●Measures for avoiding danger

Warning notes are always labelled with a signal word and sometimes also with a symbol for the specific danger.

The following signal words and danger levels are used:

 DANGER	
	Imminent danger! ► Non-observance can cause death or severe injury

 WARNING	
	Potentially dangerous situation! ► Non-observance can cause death or severe injury

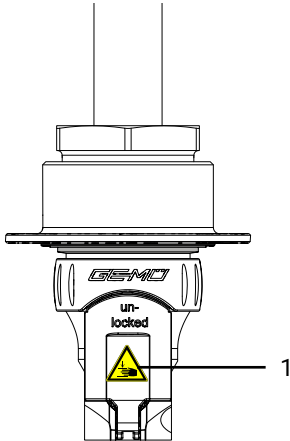
 CAUTION	
	Potentially dangerous situation! ► Non-observance can cause moderate to light injury

NOTICE	
	Potentially dangerous situation! ► Non-observance can cause damage to property

The following symbols for the specific dangers can be used within a warning note:

Symbol	Meaning
	Danger of explosion!
	The equipment is subject to pressure!
	Corrosive chemicals!
	Hot plant components!
	Risk of crushing!
	Risk of crushing due to the compressor shutting down!

1.6 Safety information on the product (example)



Item	Symbol	Meaning
1		Risk of crushing! - Do not reach into the tube crushing area.

Missing or illegible adhesive labels on the product must be attached or replaced.

2 Safety information

The safety information in this document refers only to an individual product. Potentially dangerous conditions can arise in combination with other plant components, which need to be considered on the basis of a risk analysis. The operator is responsible for the production of the risk analysis and for compliance with the resulting precautionary measures and regional safety regulations.

The document contains fundamental safety information that must be observed during commissioning, operation and maintenance. Non-compliance with these instructions may cause:

- Personal hazard due to electrical, mechanical and chemical effects
- Hazard to nearby equipment
- Failure of important functions
- Hazard to the environment due to the leakage of dangerous materials

The safety information does not take into account:

- Unexpected incidents and events, which may occur during installation, operation and maintenance
- Local safety regulations which must be adhered to by the operator and by any additional installation personnel

Prior to commissioning:

1. Transport and store the product correctly.
2. Do not paint the bolts and plastic parts of the product.
3. Carry out installation and commissioning using trained personnel.
4. Provide adequate training for installation and operating personnel.
5. Ensure that the contents of the document have been fully understood by the responsible personnel.
6. Define the areas of responsibility.
7. Observe the safety data sheets.
8. Observe the safety regulations for the media used.

During operation:

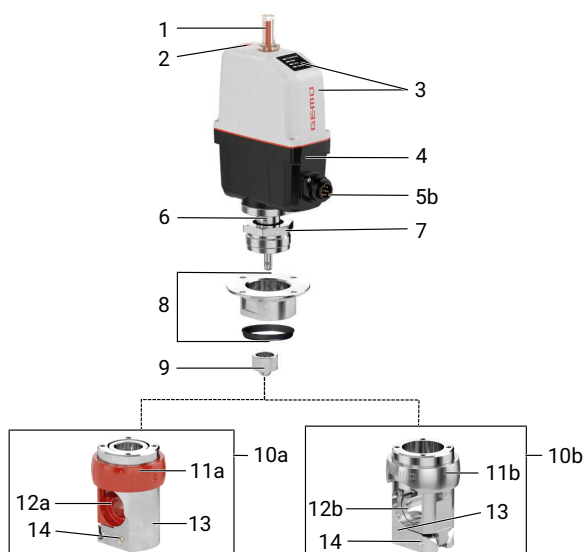
9. Keep this document available at the place of use.
10. Observe the safety information.
11. Operate the product in accordance with this document.
12. Operate the product in accordance with the specifications.
13. Maintain the product correctly.
14. Do not carry out any maintenance work and repairs not described in this document without consulting the manufacturer first.

In cases of uncertainty:

15. Consult the nearest GEMÜ sales office.

3 Product description

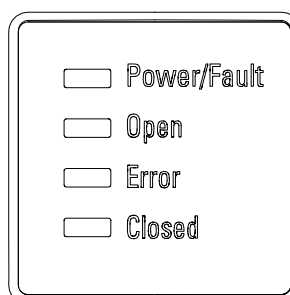
3.1 Construction



Item	Name	Materials
1	Optical position indicator	PA 12
2	Manual override	
3	Actuator top with LED display	Polyamide, 50% glass fibre
4	Actuator base	Polyamide, 50% glass fibre
5b	Electrical connection X1	
6	Distance piece	Stainless steel
7	Union nut	Stainless steel
8	Distance piece with mounting flange including EPDM seal	Stainless steel
9	Compressor	Stainless steel
10a	Valve body	Stainless steel/PA6
10b	Valve body	Stainless steel
11a	Locking ring	PA6
11b	Locking ring	Stainless steel
12a	Tube holder	PA6
12b	Tube holder	Stainless steel
13	Tube carrier	Stainless steel
14	CONEXO RFID chip	

3.2 LED displays

3.2.1 Status LEDs



LED	Colour		Function
	Standard	Inversed ¹⁾	
Power/fault	green	green	Operating indication/communication status
	red	red	
Open	orange	green	Process valve in OPEN position
Error	red	red	Error
Closed	green	orange	Process valve in CLOSED position

1) Inversed representation of the OPEN and CLOSED LEDs, adjustable via IO-Link

3.2.2 LED conditions

Status process valve	Power/fault	Open	Error	Closed
OPEN position	●	●	○	○
CLOSED position	●	○	○	●
Position unknown	●	○	○	○
IO-Link communication	☀	○	○	○
Initialization	●	☀	○	☀
		Open and Closed flash alternately		

LED conditions					
●	lit (on)	☀	flashes	○	off

3.3 Description

The GEMÜ Q50 eSyStep 2/2-way pinch valve is motorized. The eSyStep actuator is designed as an ON/OFF actuator. The valve guides a tube which is compressed from above by a compressor to control and regulate media. The compressor's specially developed contour and the tube holder's contour minimize the strain on the tube and thus increase the tubes'

service life. Tubes can be safely inserted and removed in simple steps and without tools. An optical and electrical position indicator is integrated as standard.

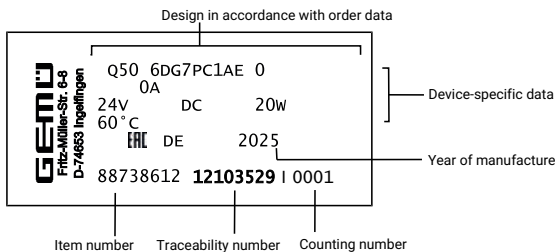
3.4 Function

The product controls or regulates (depending on version) a flowing medium by being closed or opened by a motorized actuator.

The product is equipped as standard with a mechanical position indicator as well as an electrical position and status indicator.

3.5 Product label

The product label is located on the actuator. Product label data (example):



The month of manufacture is encoded in the traceability number and can be obtained from GEMÜ. The product was manufactured in Germany.

4 Correct use

⚠ DANGER

Danger of explosion!

- ▶ Risk of death or severe injury
- Do **not** use the product in potentially explosive zones.

⚠ WARNING

Improper use of the product!

- ▶ Risk of severe injury or death
- ▶ Manufacturer liability and guarantee will be void.
- Only use the product in accordance with the operating conditions specified in the contract documentation and in this document.

NOTICE

Suitability of the product!

- ▶ The product must be appropriate for the tube's operating conditions (medium, medium concentration, temperature and pressure) and the respective ambient conditions.

The product is designed to control a working medium guided in a tube.

The product is not intended for use in potentially explosive areas.

- Use the product in accordance with the technical data.

5 Order data

The order data provide an overview of standard configurations.

Please check the availability before ordering. Other configurations available on request.

Order codes

1 Type	Code
Pinch valve, electrically operated, eSyStep	Q50

2 Tube inside diameter	Code
3.180 mm (1/8") inside diameter	2
4.760 mm (3/16") inside diameter	3
6.350 mm (1/4") inside diameter	4
7.95 mm (5/16") inside diameter	5
9.530 mm (3/8") inside diameter	6
12.700 mm (1/2") inside diameter	8
19.050 mm (3/4") inside diameter	12
25.400 mm (1") inside diameter	16

3 Tube outside diameter	Code
6.350 mm (1/4") outside diameter	DA
9.530 mm (3/8") outside diameter	DC
11.110 mm (7/16") outside diameter	DD
12.700 mm (1/2") outside diameter	DE
14.300 mm (9/16") outside diameter	DF
15.880 mm (5/8") outside diameter	DG
19.100 mm (3/4") outside diameter	DH
22.230 mm (7/8") outside diameter	DI
28.580–29.970 mm (1 1/8–1 3/16") outside diameter	DK
35.690–38.100 mm (1 13/32–1 1/2") outside diameter	DN

4 Tube carrier version	Code
Plastic design, stainless steel tube carrier and PA tube holder	7P
Stainless steel design, stainless steel tube carrier and stainless steel tube holder, stainless steel locking ring	77

5 Voltage/Frequency	Code
24 V DC	C1

6 Control module	Code
ON/OFF actuator, additional end position indicator configured for emergency power supply module (NC)	A5
ON/OFF actuator, additional end position indicator configured for emergency power supply module (NO)	A6
ON/OFF actuator, additional end position indicators	AE
Positioner	S0
Positioner, configured for emergency power supply module (NC)	S5
Positioner, configured for emergency power supply module (NO)	S6

7 Mounting option	Code
Without mounting flange, with 4 x threaded holes in the body	0
With mounting flange below	FB
With mounting flange above	FT

8 Actuator version	Code
Actuator size 0	0A
Actuator size 1	1A

9 CONEXO	Code
Without	
Integrated RFID chip for electronic identification and traceability	C

Order example

Ordering option	Code	Description
1 Type	Q50	Pinch valve, electrically operated, eSyStep
2 Tube – inside diameter	8	12.700 mm (1/2") inside diameter
3 Tube – outside diameter	DH	19.100 mm (3/4") outside diameter
4 Valve body material	7P	Plastic design, stainless steel tube carrier and PA tube holder
5 Voltage/Frequency	C1	24 V DC
6 Control module	AE	ON/OFF actuator, additional end position indicators
7 Mounting flange	FT	With mounting flange above
8 Actuator version	0A	Actuator size 0

6 Technical data

The media-conveying tubes are not part of the scope of delivery. All technical data applies solely to the valve itself. The suitability and selection of the media-conveying tubes for the intended process is the user's responsibility. For tested tube combinations that are compatible with the valve, please refer to the chapter "Tested tube combinations".

6.1 Medium

Working medium: Please observe the tube manufacturer's specifications

6.2 Temperature

Media temperature: Please observe the tube manufacturer's specifications

Ambient temperature: Actuator: 0 – 60 °C, Tube: Please observe the tube manufacturer's specifications

Storage temperature: 0 – 40 °C

6.3 Pressure

Operating pressure: max. 6 bar
Please observe the tube manufacturer's specifications

6.4 Product compliance

Machinery Directive: 2006/42/EC

EMC Directive: 2014/30/EU

RoHS Directive: 2011/65/EU

6.5 Mechanical data

Protection class: IP 65 acc. to EN 60529

Actuating speed: Max. 3 mm/s

Weight:

Size	Mounting flange	Tube holder	
		Stainless steel/PA6	Stainless steel
BG0	FT	1.65	1.69
	0	1.67	1.71
BG1	FT	2.10	2.23
	0	1.99	2.12
BG2	FB	5.38	6.07
	0	5.06	5.75

Weights in kg

Mechanical environmental conditions: Class 4M8 acc. to EN 60721-3-4:1998

Vibration: 5g acc. to IEC 60068-2-6 Test Fc

Shock: 25g acc. to 60068-2-27 Test Ea

6.6 Tested tube combinations

The following tube combinations have been tested taking into account the specifications of the respective tube manufacturer and have been found to be suitable for use in our pinch valves.*

However, the versions below are not a substitute for the user testing the tube for its suitability for the intended process.

Inside diameter (order code)	Inside diameter [inches]	Inside diameter [mm]	Outside diameter (order code)	Outside diameter [inches]	Outside diameter [mm]	Tube type	Clocking	Pressure [bar]	Service life until breakage
2	1/8"	3.18	DA	1/4"	6.35	Silicone	2/2 s	1.6	10,000 cycle duties
2	1/8"	3.18	DC	3/8"	9.53	reinforced	2/2 s	6	7250 cycle duties
3	3/16"	4.76	DC	3/8"	9.53	TPE	2/2 s	2.0	25,000 cycle duties
3	3/16"	4.76	DC	3/8"	9.53	Silicone	2/2 s	1.4	25,000 cycle duties
3	3/16"	4.76	DC	3/8"	9.53	reinforced	2/2 s	4.0	7000 cycle duties
3	3/16"	4.76	DD	7/16"	11.11	Silicone	2/2 s	1.7	25,000 cycle duties
4	1/4"	6.35	DD	7/16"	11.11	Silicone	2/2 s	1.2	10,000 cycle duties
4	1/4"	6.35	DE	1/2"	12.70	reinforced	2/2 s	6	1 x 3200 cycle duties 1 x 7700 cycle duties
4	1/4"	6.35	DE	1/2"	12.70	reinforced	2/2 s	3.8	8000 cycle duties
5	5/16"	7.94	DD	7/16"	11.11	N/A	2/2 s	1.0	23,000 cycle duties
5	5/16"	7.94	DE	1/2"	12.70	Silicone	2/2 s	1.2	20,000 cycle duties
5	5/16"	7.94	DE	1/2"	12.70	TPE	2/2 s	1.6	15,000 cycle duties
6	3/8"	9.53	DF	9/16"	14.30	Silicone	2/2 s	1.1	8900 cycle duties
6	3/8"	9.53	DG	5/8"	15.88	TPE	2/2 s	1.6	25,000 cycle duties
6	3/8"	9.53	DG	5/8"	15.88	reinforced	2/2 s	6	4750 cycle duties
6	3/8"	9.53	DG	5/8"	15.88	reinforced	2/2 s	3.8	2700 cycle duties
8	1/2"	12.70	DH	3/4"	19.05	TPE	2/2 s	1.5	25,000 cycle duties
8	1/2"	12.70	DI	7/8"	22.32	reinforced	2/2 s	6	4750 cycle duties
12	3/4"	19.05	DK	1 1/8"	28.58	reinforced	2/2 s	6	1650 cycle duties
12	3/4"	19.05	DK	1 1/8"	28.58	Silicone	2/2 s	1	25,000 cycle duties
12	3/4"	19.05	DK	1 1/6"	29.97	double reinforced	2/2 s	6	2000 cycle duties
16	1"	25.40	DN	1 13/32"	35.69	reinforced	2/2 s	4	3000 cycle duties

Inside diameter (order code)	Inside diameter [inches]	Inside diameter [mm]	Outside diameter (order code)	Outside diameter [inches]	Outside diameter [mm]	Tube type	Clocking	Pressure [bar]	Service life until breakage
16	1"	25.40	DN	1 7/16"	36.32	double reinforced	2/2 s	6	3150 cycle duties

* Test medium: Water. The results in use may vary from those of the test environment due to the influence of deviating media.

6.7 Actuator's duty cycle and service life

If there is inadequate force to compress the tube, the force of the actuator can be adapted via the IO-Link using the config files.

Service life:

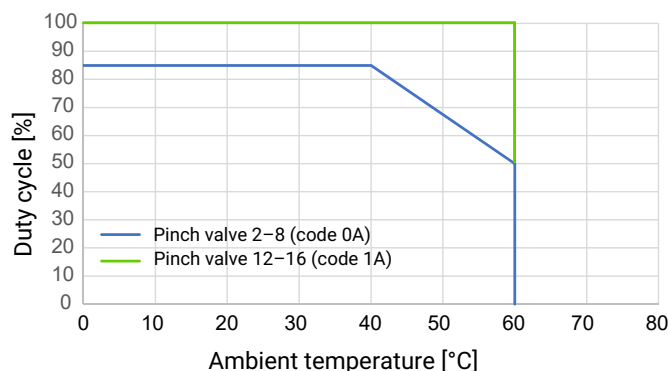
Actuator size 0: Minimum 500,000 switching cycles at room temperature and permissible duty cycle.

Actuator size 1: Minimum 100,000 switching cycles at room temperature and permissible duty cycle.

Duty cycle:

Control module – Open/Close control (code A5, A6, AE)

Duty cycle at full valve stroke and 10 minutes cycle time.



NOTICE

- The specified characteristics and values apply to the default setting.
- With reduced forces, higher duty cycles and/or higher ambient temperatures are possible. At higher force settings the duty cycle and/or ambient temperature is reduced.
- IO-Link: Index 0x90 - Subindex 2 - Force

6.8 Electrical data

Supply voltage U_v : 24 V DC $\pm$ 10%

Rating: Actuator size 0 (code 0A) 20 W
Actuator size 1 (code 1A) 60 W

Operation: Stepper motor, self-locking

Reverse polarity protection: Yes

6.8.1 Digital input signals

Inputs: Function selectable via IO-Link (see table Overview of available functions – Input and output signals)

Input voltage: 24 V DC

Logic level "1": > 15.3 V DC

Logic level "0": < 5.8 V DC

Input current: typically < 0.5 mA

6.8.2 Digital output signals

Outputs: Function selectable via IO-Link (see table Overview of available functions – Input and output signals)

Type of contact:	Push-Pull
Switching voltage:	Power supply U_v
Switching current:	≤ 140 mA
Short-circuit proof:	Yes

6.8.3 Communication

Interface:	IO-Link
Function:	Parameterization/process data
Transmission rate:	38400 baud
Frame type in Operate:	2.5 (eSyStep ON/OFF, code AE, A5, A6)
Min. cycle time:	2.3 ms (eSyStep ON/OFF, code AE, A5, A6)
Vendor-ID:	401
Device-ID:	1906701 (eSyStep ON/OFF, code AE, A5, A6)
Product-ID:	eSyStep On/Off (code AE, A5, A6)
ISDU support:	Yes
SIO operation:	Yes
IO-Link specification:	V1.1

IODD files can be downloaded via <https://ioddfinder.io-link.com/> or www.gemu-group.com.

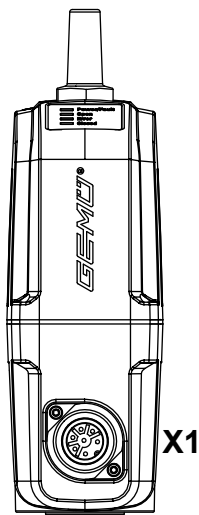
7 Electrical connection

NOTICE

Appropriate cable socket/appropriate mating connector

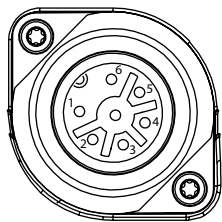
► The appropriate connector is included for X1.

7.1 Position of the connectors



7.2 Electrical connection

7.2.1 Connection X1



7-pin plug, Binder, type 693

Pin	Signal name
1	Uv, 24 V DC supply voltage
2	GND
3	Digital input 1
4	Digital input 2
5	Digital input/output
6	Digital output, IO-Link
7	n.c.

7.3 Overview of available functions – Input and output signals

NOTICE

- The factory default setting "Configured for emergency power supply module" is reset to default settings when a reset is carried out.

NOTICE

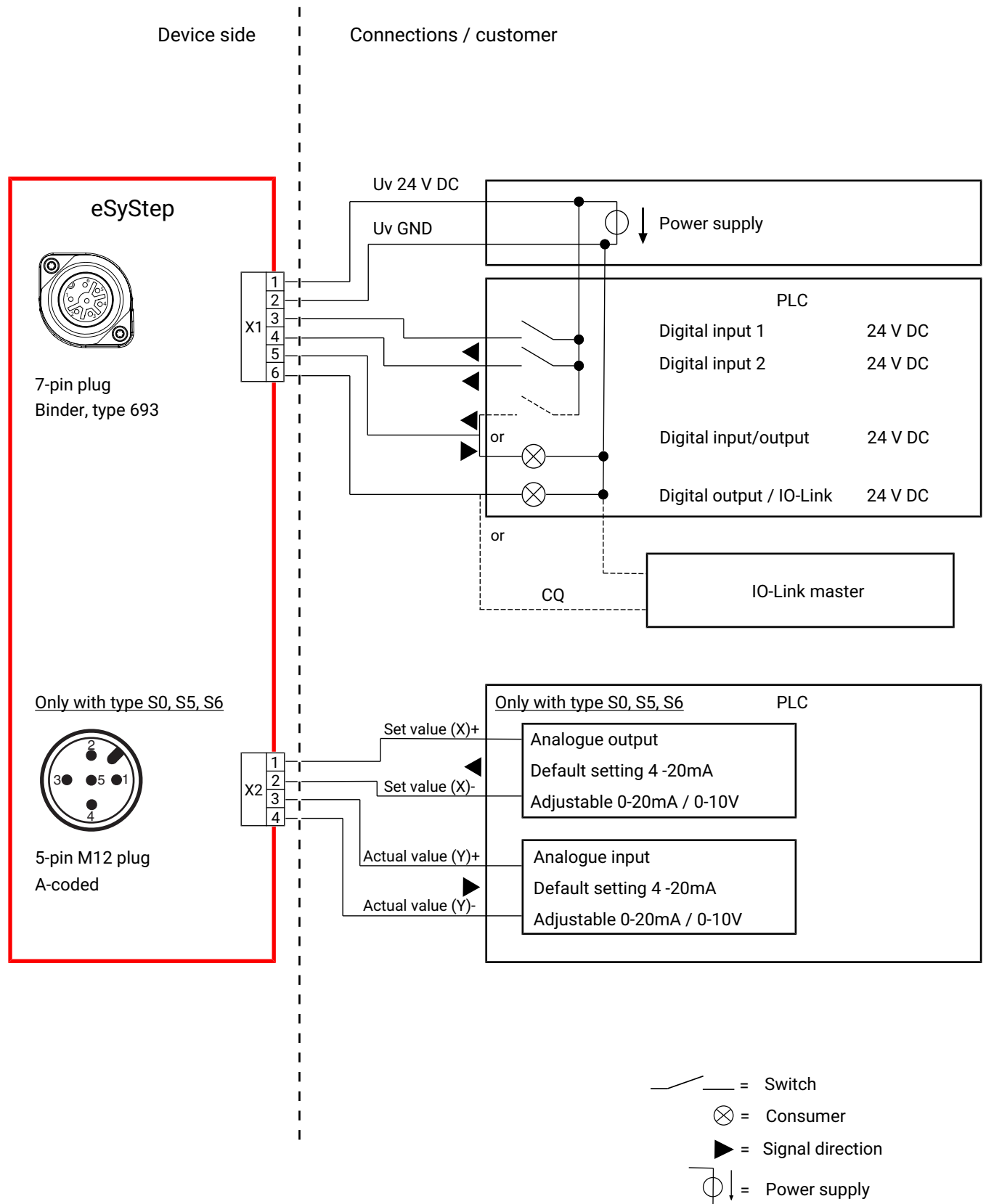
- When configuring the emergency power module (code A5 / A6), the control of the valve changes. Valve is controlled 1-pole via digital input 1. Level logic 1 moves the valve OPEN, level logic 0 moves the valve CLOSE.

NOTICE

- When the digital inputs for OPEN and CLOSE are activated simultaneously, the defined error position is approached.

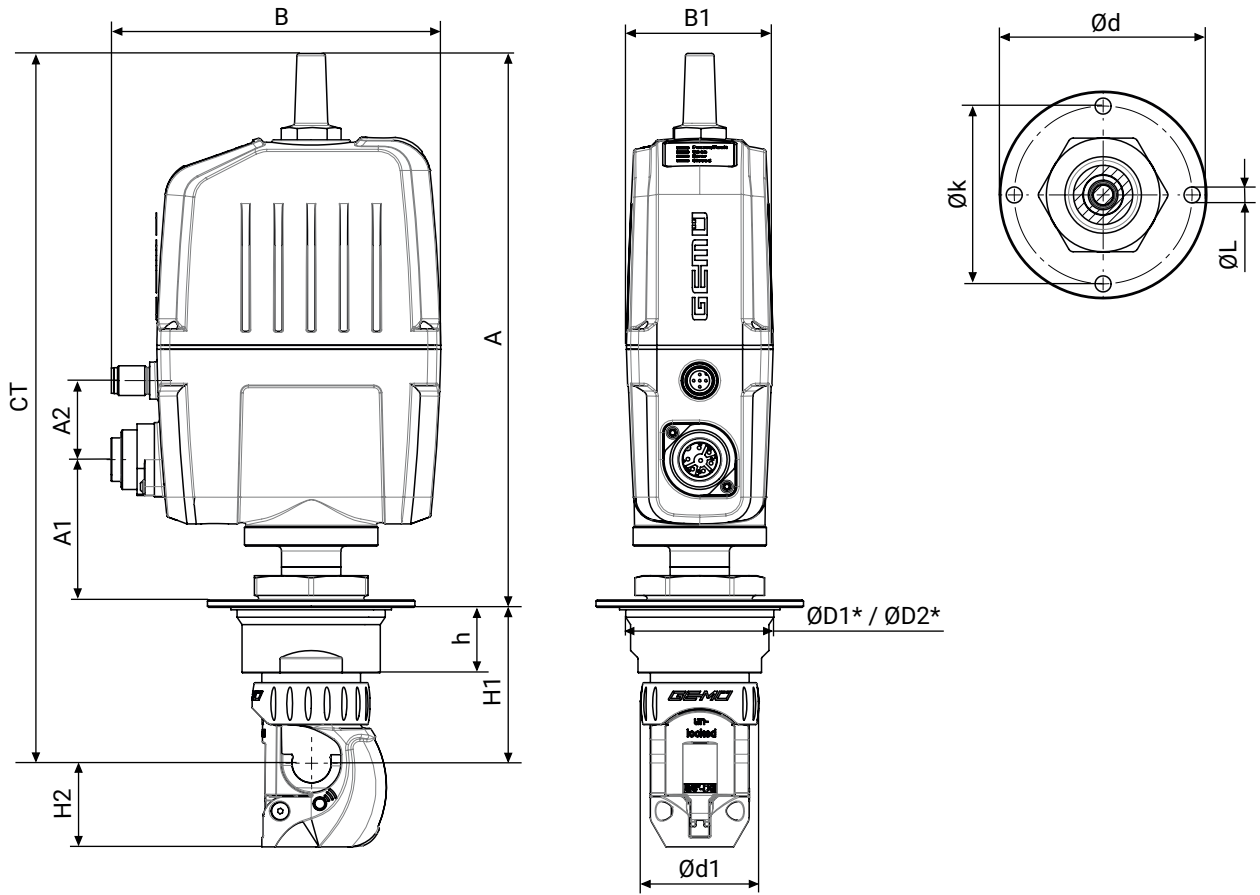
	Function	Control module AE	Control module A5, A6
		Default settings	Factory default setting "Configured for emergency power supply module"
Digital input 1	Off/Open/Closed/Safe/On/ Initialization	Open	Open
Digital input 2	Off/Open/Closed/Safe/On/ Initialization	Closed	Safe/On
Digital input/output	Open/Closed/Error/Error and warning/Initialization	Open	Open
Digital output	Open/Closed/Error/Error and warning	Closed	Closed

7.4 Connection diagram



8 Dimensions

8.1 Size BG0

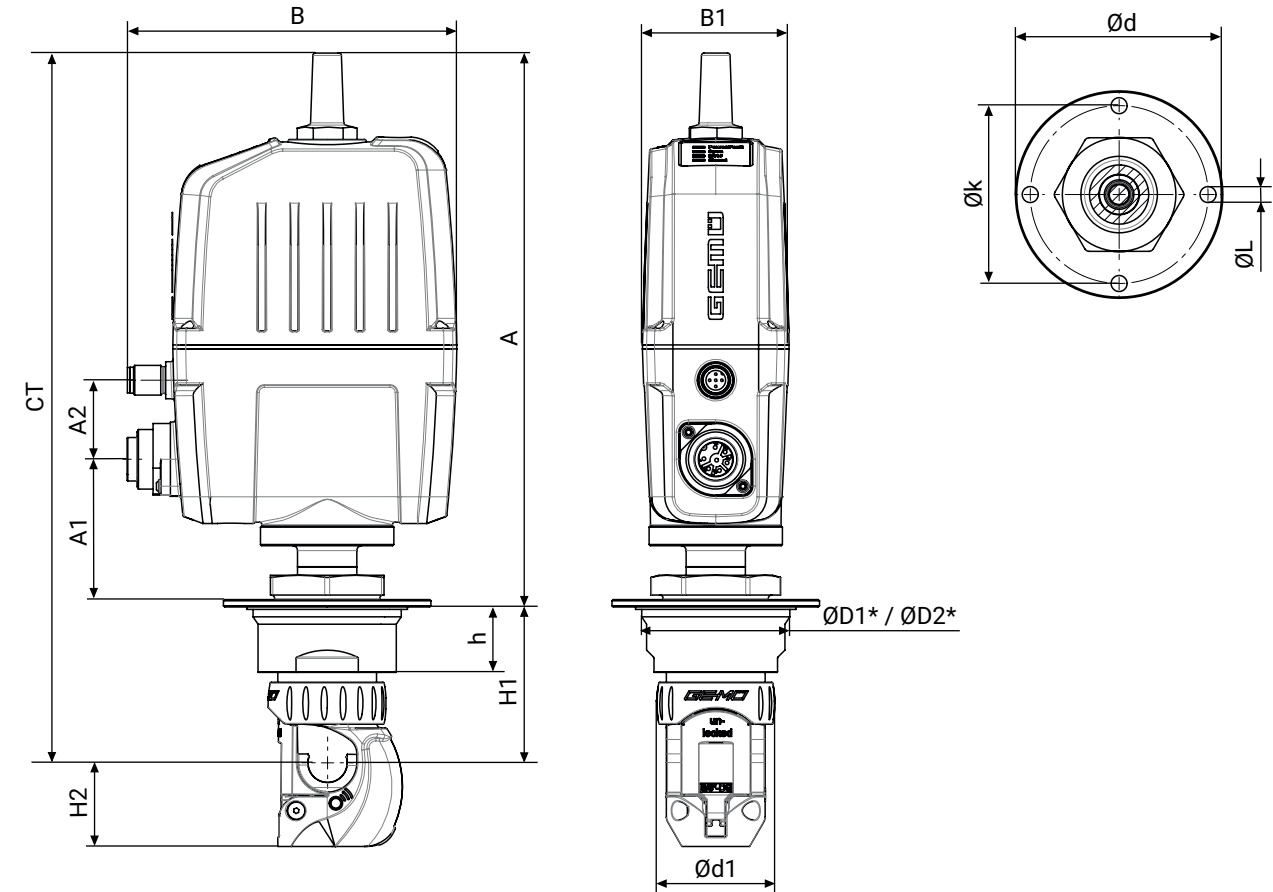


A	A1	A2	B	B1	CT	ØD1*	ØD2*	Ød	Ød1	H1	H2	Øk	ØL	h
230.9	66.4	33.2	133.5	59.4	273.9	39.0	42.0	58.0	30.5	43.0	15.6	49.0	4.5	17.1

Dimensions in mm

* D1 = diameter without seal, D2 = diameter with seal

8.2 Size BG1

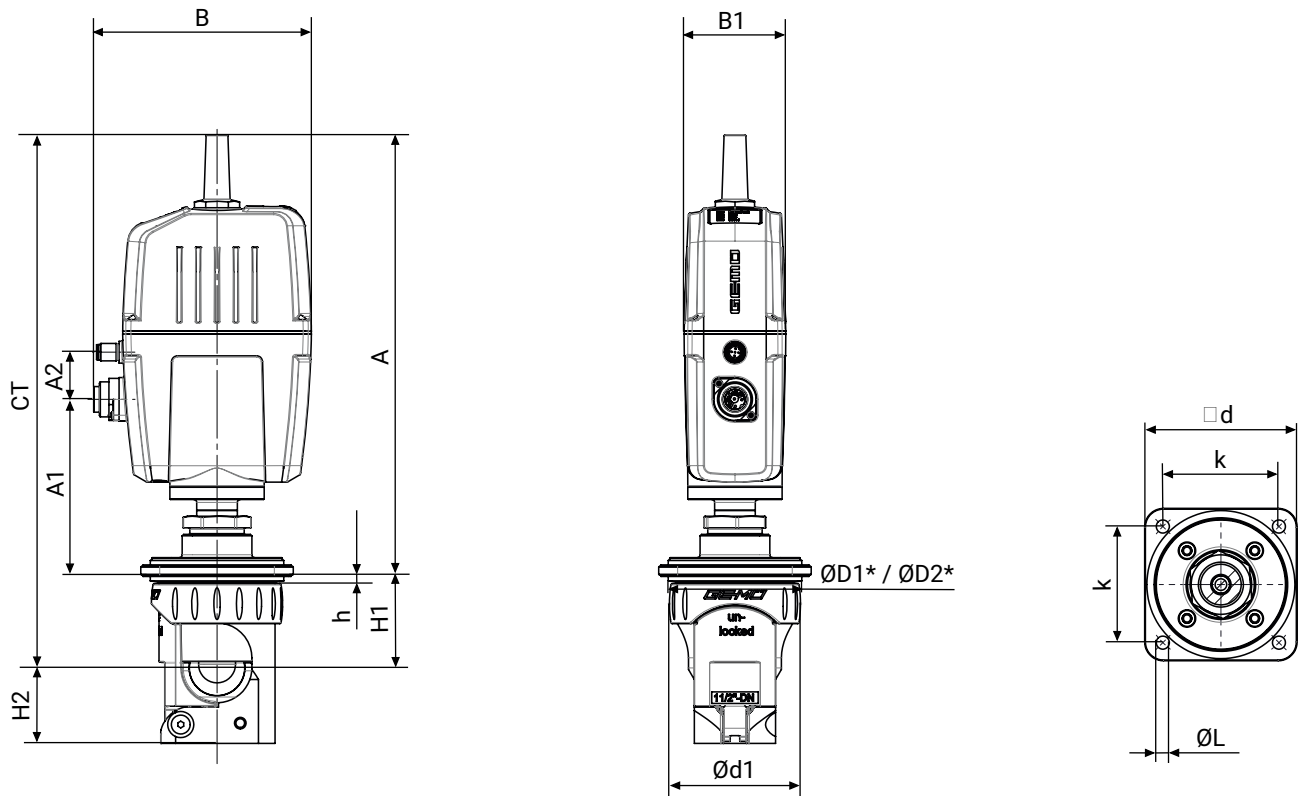


A	A1	A2	B	B1	CT	ØD1*	ØD2*	Ød	Ød1	H1	H2	Øk	ØL	h
230.9	66.4	33.2	133.5	59.4	273.9	56.0	60.0	84.0	47.8	63.0	26.0	72.0	6.5	26.5

Dimensions in mm

* D1 = diameter without seal, D2 = diameter with seal

8.3 Size BG2

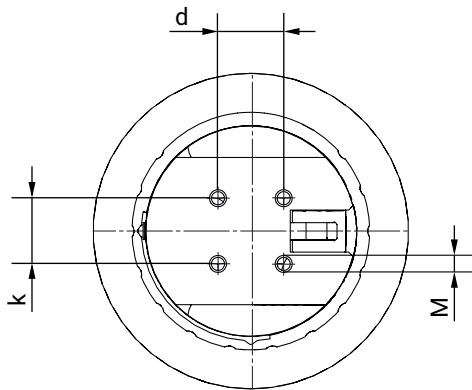


A	A1	A2	B	B1	CT	ØD1*	ØD2*	d	Ød1	H1	H2	k	ØL	h
303.0	115.0	32.5	150.0	70.0	367.0	80.0	92.0	105.0	90.4	64.0	52.0	80.0	9.0	6.0

Dimensions in mm

* D1 = diameter without seal, D2 = diameter with seal

8.4 Valve body, without mounting flange



Size	d	k	M
BG0	7.0	7.0	M2
BG1	12.0	12.0	M4
BG2	25.0	25.0	M6

Dimensions in mm

9 Manufacturer's information

9.1 Delivery

- Check that all parts are present and check for any damage immediately upon receipt.

The product's performance is tested at the factory. The scope of delivery is apparent from the dispatch documents and the design from the order number.

9.2 Packaging

The product is packaged in a cardboard box which can be recycled as paper.

9.3 Transport

1. Only transport the product by suitable means. Do not drop. Handle carefully.
2. After the installation dispose of transport packaging material according to relevant local or national disposal regulations / environmental protection laws.

9.4 Storage

1. Store the product free from dust and moisture in its original packaging.
2. Avoid UV rays and direct sunlight.
3. Do not exceed the maximum storage temperature (see chapter "Technical data").
4. Do not store solvents, chemicals, acids, fuels or similar fluids in the same room as GEMÜ products and their spare parts.
5. Close the compressed air connections with protection caps or sealing plugs.

10 Installation

10.1 Preparing for installation

⚠ WARNING	
	The equipment is subject to pressure! ▶ Risk of severe injury or death ● Depressurize the plant or plant component. ● Completely drain the plant or plant component.
⚠ WARNING	
	Corrosive chemicals! ▶ Risk of caustic burns ● Wear appropriate protective gear. ● Completely drain the plant.

⚠ CAUTION	
	Hot plant components! ▶ Burns ● Only work on plant that has cooled down. ● Wear protective gear.
⚠ CAUTION	
Use as step! ▶ Damage to the product ▶ Risk of slipping-off ● Choose the installation location so that the product cannot be used as a foothold. ● Do not use the product as a step or a foothold.	
NOTICE	
Suitability of the product! ▶ The product must be appropriate for the tube's operating conditions (medium, medium concentration, temperature and pressure) and the respective ambient conditions.	
NOTICE	
Requirements for tube lines used! ▶ Use tube lines suitable for the application, see manufacturer's information. ● Only use undamaged tube lines.	
NOTICE	
Lay tube lines professionally! ▶ Lay tube lines professionally and do not bend them below the minimum bending radius, see manufacturer's information. ● Do not kink or twist the tube lines.	

NOTICE

Tools!

- The tools required for installation and assembly are not included in the scope of delivery.
 - Use appropriate, functional and safe tools.
1. Ensure the product is suitable for the relevant application.
 2. Check the technical data of the product and the materials.
 3. Keep appropriate tools ready.
 4. Use appropriate protective gear as specified in plant operator's guidelines.
 5. Observe appropriate regulations for connections.
 6. Installation work must be performed by trained personnel.
 7. Shut off plant or plant component.
 8. Secure the plant or plant component against recommissioning.
 9. Depressurize the plant or plant component.
 10. Completely drain the plant or plant component and allow it to cool down until the temperature is below the media vaporization temperature and cannot cause scalding.
 11. Pay attention to the installation position (see chapter "Installation position").

10.2 Installation position

The installation position of the product is optional.

10.3 Mounting without mounting flange

1. Before mounting the valve body, machine the housing in accordance with the borehole pattern in the chapter "Dimensions" so that the valve body can be secured to the housing.
2. Secure the valve body to the housing using four screws.
3. Re-attach or reactivate all safety and protective devices.

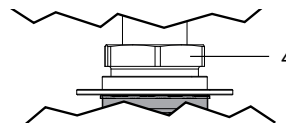
10.4 Mounting with mounting flange

1. Before mounting the actuator, machine the housing in accordance with the borehole pattern in the chapter "Dimensions" so that the valve body can be guided through the recess.
2. Guide the valve body through the recess in the housing. The actuator's mounting flange must be flush with the housing.
3. Connect the mounting flange and housing using appropriate screws and washers (not included in the scope of delivery).

10.5 Turning the actuator

NOTICE

- Actuators can be turned for positioning of the connections.



1. Undo union nut **4**.
2. Turn the actuator to the required position.
3. Tighten union nut **4** (see table for torques).

Size	Torque
BG0	Max. 20 Nm
BG1	Max. 30 Nm
BG2	Max. 50 Nm

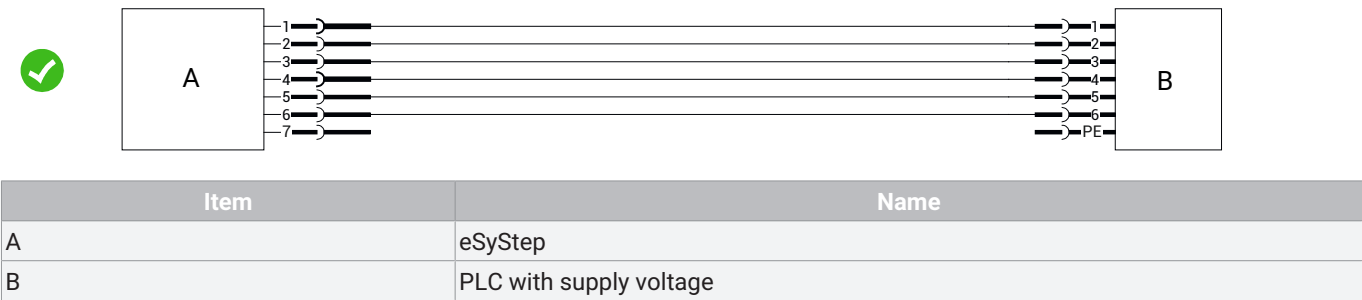
11 Specific data IO-Link (pin 6)

IO-Link process data and parameters can be set via pin 6 for the motorized linear actuator eSyStep. The assignment of the connectors and the current consumption of the actuator are non-compliant with the IO-Link specification.

11.1 Operation on IO-Link

11.1.1 Operation on PLC as a 24 V device

The motorized actuator GEMÜ eSyStep can be operated directly in a PLC control unit without limitations. Technical data of the product and of PLC must be complied with.



11.1.2 Operation on PLC and additional parameterization via USB master with galvanic isolation

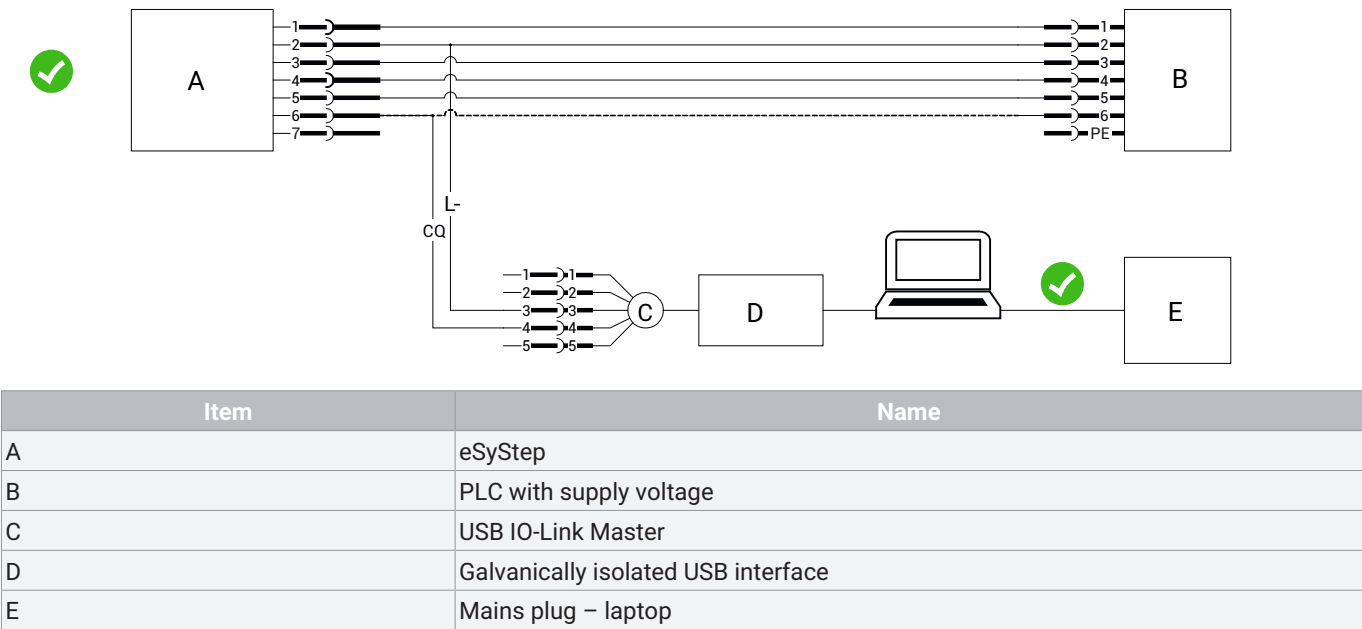
Basics

When operating the product on a PLC control unit, a parameterization via a USB IO-Link master is possible at the same time. In this case, a galvanically isolated USB interface must be used. The PC/laptop can be used as usual and all peripheral devices can remain connected.

Connection

- 1. Connect **pin 3 (L-)** of the master with **pin 2 (GND)** of the product.
- 2. Connect **pin 4 (CQ)** of the master with **pin 6** of the product.

During IO-Link operation, pin 6 **cannot** be evaluated by the PLC control unit as an output signal.



11.1.3 Operation on PLC and additional parameterization via USB master without galvanic isolation

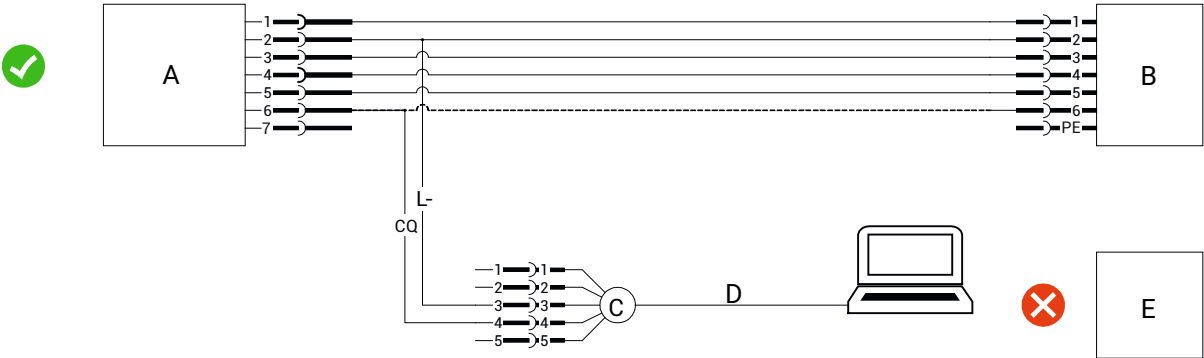
Basics

Only one laptop can be used if no galvanic isolation is available for the USB interface during communication via a USB IO-Link master. No other peripheral devices may be connected to the laptop. The laptop may only be operated without a power supply unit.

If further peripheral devices and the power supply unit are not disconnected, different ground potentials to the product can result in excessive compensating currents. These can damage the USB interface of the laptop, the connected peripheral devices or the USB IO-Link master.

Connection

- 1. Connect **pin 3 (L-)** of the master with **pin 2 (GND)** of the product.
 - 2. Connect **pin 4 (CQ)** of the master with **pin 6** of the product.
- During IO-Link operation, pin 6 **cannot** be evaluated by the PLC control unit as an output signal.



Item	Name
A	eSyStep
B	PLC with supply voltage
C	USB IO-Link Master
D	USB interface
E	Mains plug – laptop

11.1.4 Direct operation on the IO-Link master

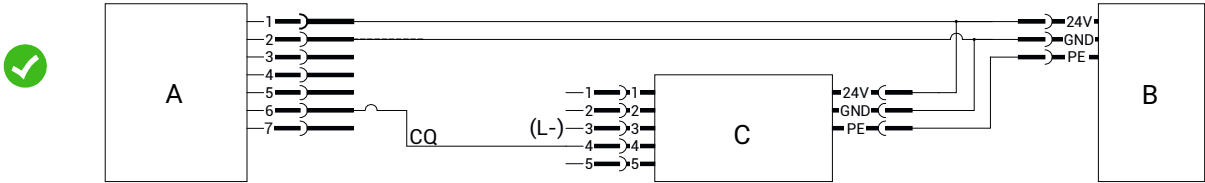
Basics

If the product is to be operated on an IO-Link master, it must be ensured that the **GND** levels in the product and in the IO-Link master have the same potential so that there are no compensating currents which would cause damage in the system. This can be made possible using several procedures.

11.1.4.1 Identical power supply

The IO-Link master is operated from the same power supply as the product.

- Connect **pin 4 (CQ)** of the master with **pin 6** of the product.
- However, **pin 3 (L-)** of the master should **not** be connected to **pin 2 (GND)** of the product under any circumstances. This prevents a ground loop and no unexpected high currents can occur via **pin 3 (L-)** which can damage the master.

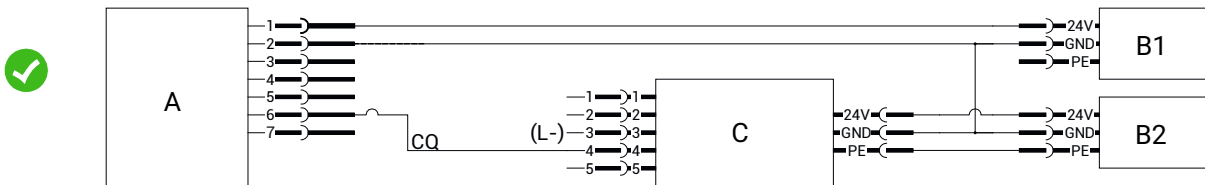


Item	Name
A	eSyStep
B	Supply voltage
C	USB IO-Link Master

11.1.4.2 Separate power supply, GND-connected

The IO-Link master and the product can also be operated with different power supply sources if the **GND** of both power supply sources is connected. In this case, the master is connected as when the power supply is identical

- Connect **pin 4 (CQ)** IO-Link master with **pin 6** of the product.
- Do **not** connect (**pin 3**) L- IO-Link master.



Item	Name
A	eSyStep
B1 and B2	Supply voltages
C	USB IO-Link Master

11.2 Process data

The motorized linear actuator has IO-Link process data. This data is transmitted cyclically with each IO-Link telegram.

Note: To control the valve via IO-Link process data, parameter index 0x50 – subindex 4 (Basic Settings – IO-Link process data) must be set to 1 (Enable).

Master → Device

Name	Bit	Values
Drive go Open	0	0 → Actuator does not move into position Open
		1 → Actuator moves into position Open
Drive go Close	1	0 → Actuator does not move into position Closed
		1 → Actuator moves into position Closed
Start Initialization	2	0 → Normal operation
		1 → Initialization mode
Locate	3	0 → Off
		1 → On

Device → Master

Name	Bit	Values
Valve position Open	0	0 → Process valve not in Open position
		1 → Process valve in Open position
Valve position Close	1	0 → Process valve not in Closed position
		1 → Process valve in Closed position
Operating mode	2	0 → Normal operation
		1 → Initialization mode

11.3 Parameter overview

NOTICE

► All IO-Link parameters that contain sub-indexes can also be addressed in bundles via sub-index 0.

Index	Sub-Index	Access rights	Index name	Parameter	Function	Default settings	Setting options
0x02	0	W	System command		Transmission of commands for block parameterization and data storage		0x01 to 0x06 0x82 0xA2
0x03	1	R/W	Data storage index	Data storage cmd	Saving and restoring parameter data for device identical in construction		
	2	RO		State property			
	3	RO		Data storage size			
	4	RO		Parameter checksum			
	5	RO		Index list			
0x0C	1	R/W	Device access locks	Parameter (write) access	Parameter write protection		0 → unlocked 1 → locked
	2	R/W		Data storage	Data memory		0 → unlocked 1 → locked
	3	R/W		Local parameterization	Local parameterization		0 → unlocked 1 → locked
	4	R/W		Local user interface	Local user interface		0 → unlocked 1 → locked
0x0D	0	RO	Profile characteristics		Supported Device Profile IDs, Common Application Profile IDs, Function Class IDs		0x8000 (Device Ident. Objects) 0x8002 (Process Data Mapping) 0x8003 (Diagnosis) 0x8100 (Ext. Identification)
0x0E	0	RO	Process data input descriptor		Data format of input process data		0x00 (Bit offset) 0x03 (Type Length) 0x01 (DataType -> BoolT)
0x0F	0	RO	Process data output descriptor		Data format of output process data		0x00 (Bit offset) 0x04 (Type Length) 0x01 (DataType -> BoolT)
0x10	0	RO	Vendor name		Read out manufacturer name		"GEMUE"
0x12	0	RO	Product name		Read out device name		"eSyStep On/Off"
0x13	0	RO	Product ID		Read out product ID		"eSyStep On/Off"
0x15	0	RO	Serial number		Read out serial number		"XXXXXXXX/YYYY"
0x16	0	RO	Hardware revision		Read out hardware version		"Rev. XX/XX"
0x17	0	RO	Firmware revision		Read out software version		"V X.X.X.X."

Index	Sub-Index	Access rights	Index name	Parameter	Function	Default settings	Setting options
0x18	0	R/W	Application specific tag		Text with 32 characters can be entered		*****"
0x19	0	R/W	Function tag		Text with 32 characters can be entered		*****"
0x1A	0	R/W	Location tag		Text with 32 characters can be entered		*****"
0x24	0	RO	Device status		(Simple) device status		0 → Operating properly 2 → Out of specification 4 → Failure
0x25	0	RO	Device status		Detailed device status		
0x40	0	RO	Actuator size		Read out actuator size	Depending on the actuator size used	0 → Actuator size 0 1 → Actuator size 1 2 → Actuator size 2
0x4B	1	R/W	Function digital inputs	Input 1	Configure digital input 1	1	0 → Off 1 → Open 2 → Close 3 → Safe/On 4 → Init
	2	R/W		Input 2	Configure digital input 2	2	0 → Off 1 → Open 2 → Close 3 → Safe/On 4 → Init
0x4C	1	R/W	Function digital in-/output 1	In- / output 1	Configure digital inputs/outputs	0	0 → Output open 1 → Output close 2 → Output error 3 → Output error & warning 4 → Input init
	2	R/W		Type in- / output 1	Configure type of digital inputs/outputs	0	0 → Push-pull 1 → NPN 2 → PNP
0x4D	0	R/W	Function digital output 2		Configure digital output	1	0 → Output open 1 → Output close 2 → Output error 3 → Output error & warning
0x4E	1	R/W	Logic digital inputs / outputs	Input 1	Configure logical digital input 1	0	0 → Active high 1 → Active low
	2	R/W		Input 2	Configure logical digital input 2	0	0 → Active high 1 → Active low
	3	R/W		Input / output 1	Configure logical digital input/output	0	0 → Active high 1 → Active low
	4	R/W		Output 2	Configure logical digital output	0	0 → Active high 1 → Active low

Index	Sub-Index	Access rights	Index name	Parameter	Function	Default settings	Setting options
0x4F	0	R/W	Error action	Error action	Set safety position	2	0 → Hold 1 → Open 2 → Close
0x50	1	R/W	Basic settings	Inversion of LED colours	Activate / deactivate inversion of LEDs	0	0 → Standard 1 → Inversed
	2	R/W		On site initialization	Activate / deactivate on site initialization	0	0 → Enabled 1 → Disabled
	3	R/W		Initialization mode	Set initialization mode auto / manual	0	0 → Automatic 1 → Manual
	4	R/W		IO-Link process data	Activate/deactivate use of IO-Link process data	0	0 → Disabled 1 → Enabled
0x51	1	R/W	Actuator position feedback	Open request	Request valve position OPEN	900 (90.0%)	30 ... 970 (3.0 ... 97.0%)
	2	R/W		Close request	Request valve position CLOSED	100 (10.0%)	30 ... 970 (3.0 ... 97.0%)
	3	RO		Open real	Real valve position OPEN		0 ... 4095
	4	RO		Close real	Real valve position CLOSED		0 ... 4095
0x53	1	RO	Initialized positions	Open	Analog value valve position OPEN		0 ... 4095
	2	RO		Close	Analogue value valve position CLOSED		0 ... 4095
	3	RO		Stroke	Read out the analog value for stroke (difference between OPEN and CLOSED).		0 ... 4095
0x55	1	RO	Calibrated positions	Max.	OPEN end position		0 ... 4095
	2	RO		Min.	CLOSED end position		0 ... 4095
0x56	1	R/W	Cycle counter	User	Customer switching cycles (resettable)	0	0 ... 16.777.215
	2	RO		Total	Total of switching cycles (not resettable)	0	0 ... 16.777.215
0x57	1	RO	Failure counter	Undervoltage	Number of undervoltage errors (U < 17.4)	0	0 ... 65.535
	2	RO		Temperature error	Number of errors or switch-offs of the actuator due to overtemperature	0	0 ... 65.535
	3	RO		Motor unable to move	Motor fault / motor blocked	0	0 ... 65.535
	4	RO		Internal error	Internal error of the actuator	0	0 ... 65.535

Index	Sub-Index	Access rights	Index name	Parameter	Function	Default settings	Setting options
	5	RO		Emergency power	Supply voltage low / activation of Save/ on input	0	0 ... 65.535
	6	RO		Potifail open	Valve position OPEN error	0	0 ... 65.535
	7	RO		Potifail close	Valve position CLOSED error	0	0 ... 65.535
	8	RO		Overcurrent out 1	Overcurrent / short-circuit digital output 1	0	0 ... 65.535
	9	RO		Overcurrent out 2	Overcurrent / short-circuit digital output 2	0	0 ... 65.535
0x60	1	RO	Analog values	Potentiometer	Analog value potentiometer		0 ... 4095
	2	RO		Supply voltage	Analog value supply voltage		0 ... 4095
	3	RO		Temperature	Analog value temperature sensor		0 ... 4095
0x62	1	RO	Operating times	Open	Operating time OPEN	0	0 to 255 (0 to 25.5s)
	2	RO		Close	Operating time CLOSE	0	0 to 255 (0 to 25.5s)
0x90	1	R/W	Drive sets	Speed	Speed – average traversing range	3	1 ... 3
	2	R/W		Force	Force, dependent on valve used		1 ... 6

11.4 Parameter

The motorized linear actuator eSyStep supports parameter data in the ISDU (Index Service Data Unit). Parameters can be transmitted non-cyclically with ISDU. Block parametrization and data storage are also supported.

11.4.1 System command

The commands required for block parametrization and data storage are transmitted with the **System command** parameter.

Index	Sub-Index	Off-set	Access Rights	Length	Index name	Parameter	Type	Values
0x02	0	0	W	1 byte	System command		UIntegerT	0x01 to 0x06
								0x82
								0xA2

Description of parameter values

Index name	Parameter	Values	Description
System command		0x01 to 0x06	Access to IO-Link
		0x82	Reset product to default settings *
		0xA2	Reset customized cycle counter

* Except the index 0x90 settings – Drive Sets, these are not reset.

11.4.2 Data storage index

Changes to the parameters are stored in the IO-Link master with the **Data storage index** parameter and restored with a IO-Link device identical in construction when replaced. To do so, the **Data storage** parameter must be enabled in the Device access locks (see Chapter 11.4.3, page 31) parameter. The parameters are automatically replaced via the IO-Link master.

Index	Sub-Index	Off-set	Access Rights	Length	Index name	Parameter	Type	Values
0x03	1	0	R/W	1 byte	Data storage index	Data Storage Cmd	UIntegerT8	
	2	8	RO	1 byte		State Property	UIntegerT8	
	3	16	RO	4 bytes		Data Storage Size	UIntegerT32	
	4	48	RO	4 bytes		Parameter Check-sum	UIntegerT32	
	5	80	RO	41 bytes		Index List	OctetStringT	

11.4.3 Device access locks

Access to the parameters can be controlled with the **Device access locks** parameter.

Index	Sub-Index	Off-set	Access Rights	Length	Index name	Parameter	Type	Values
0x0C	1	0	R/W	1 bit	Device access locks	Parameter (write) access	BooleanT	0
								1
	2	1	R/W	1 bit		Data storage	BooleanT	0
								1
	3	2	R/W	1 bit		Local parameterization	BooleanT	0
								1
	4	3	R/W	1 bit		Local user interface	BooleanT	0
								1

Description of parameter values

Index name	Parameter	Values	Description
Device access locks	Local user interface	0	Enable write access
		1	Block write access
	Data storage	0	Enable storage of parameter data in the IO-Link master
		1	Block storage of parameter data in the IO-Link master
	Local parameterization	0	Enable local parameterization
		1	Block local parameterization
	Local user interface	0	Enable local user interface
		1	Block local user interface

11.4.4 Profile Characteristics

The **Profile Characteristics** parameter specifies which DeviceProfileIDs, CommonApplicationProfileIDs and FunctionClassIDs are supported.

Index	Sub-Index	Off-set	Access Rights	Length	Index name	Parameter	Type	Values
0x0D	0	0	RO	8 bytes	Profile Characteristics		ArrayT	0x8000
								0x8002
								0x8003
								0x8100

Description of parameter values

Index name	Parameter	Values	Description
Profile Characteristics		0x8000	Device identification objects
		0x8002	Process data mapping
		0x8003	Diagnostics
		0x8100	External identification

11.4.5 ProcessData Input Descriptor

The **ProcessData Input Descriptor** parameter describes the data format of the process data. Thus the master receives information about the process data without IODD.

Index	Sub-Index	Off-set	Access Rights	Length	Index name	Parameter	Type	Values
0x0E	0	0	RO	3 byte	ProcessData Input Descriptor		ArrayT	0x00 0x03 0x01

Description of parameter values

Index name	Parameter	Values	Description
ProcessData Input Descriptor		0x00	Bit offset
		0x03	Type length
		0x01	Data type -> BoolT

11.4.6 ProcessData Output Descriptor

The **ProcessData Output Descriptor** parameter describes the data format of the process data. Thus the master receives information about the process data without IODD.

Index	Sub-Index	Off-set	Access Rights	Length	Index name	Parameter	Type	Values
0x0F	0	0	RO	3 byte	ProcessData Output Descriptor		ArrayT	0x00 0x04 0x01

Description of parameter values

Index name	Parameter	Values	Description
ProcessData Output Descriptor		0x00	Bit offset
		0x04	Type length
		0x01	Data type -> BoolT

11.4.7 Vendor name

The manufacturer name can be read out in ASCII format with the **Vendor name** parameter.

Index	Sub-Index	Off-set	Access Rights	Length	Index name	Parameter	Type	Values
0x10	0	0	RO	5 bytes	Vendor name		StringT	"GEMUE"

11.4.8 Product name

The device name can be read out in ASCII format with the **Product name** parameter.

Index	Sub-Index	Off-set	Access Rights	Length	Index name	Parameter	Type	Values
0x12	0	0	RO	14 bytes	Product name		StringT	"eSyStep On/Off"

11.4.9 Product ID

The product ID can be read out in ASCII format with the **Product ID** parameter.

Index	Sub-Index	Off-set	Access Rights	Length	Index name	Parameter	Type	Values
0x13	0	0	RO	14 bytes	Product ID		StringT	"eSyStep On/Off"

11.4.10 Serial number

The serial number of the device can be read out with the **Serial number** parameter.

The serial number consists of an 8-digit traceability number, a forward slash and a 4-digit index.

Index	Sub-Index	Off-set	Access Rights	Length	Index name	Parameter	Type	Values
0x15	0	0	RO	13 bytes	Serial number		StringT	"XXXXXXXX/YYY"

11.4.11 Hardware revision

The circuit boards' version can be read out with the **Hardware revision** parameter.

The hardware version is displayed with the 2-digit version number of the basic assembly and the 2-digit version number of the OPEN/CLOSED or positioner assembly.

Index	Sub-Index	Off-set	Access Rights	Length	Index name	Parameter	Type	Values
0x16	0	0	RO	10 bytes	Hardware revision		StringT	"Rev. XX/XX"

11.4.12 Firmware revision

The software version can be read out with the **Firmware revision** parameter.

Index	Sub-Index	Off-set	Access Rights	Length	Index name	Parameter	Type	Values
0x17	0	0	RO	9 bytes	Firmware revision		StringT	"V X.X.X.X"

11.4.13 Application specific tag

A text with 32 characters can be stored in the device with the **Application specific tag** parameter.

For example, installation location, function, installation date, etc.

Index	Sub-Index	Off-set	Access Rights	Length	Index name	Parameter	Type	Values
0x18	0	0	R/W	32 bytes	Application specific tag		StringT	"***** "

11.4.14 Function tag

A text with 32 characters can be stored in the device with the **Function tag** parameter.

For example, installation location, function, installation date, etc.

Index	Sub-Index	Off-set	Access Rights	Length	Index name	Parameter	Type	Values
0x19	0	0	R/W	32 bytes	Function tag		StringT	„*****“

11.4.15 Location tag

A text with 32 characters can be stored in the device with the **Location tag** parameter.

For example, installation location, function, installation date, etc.

Index	Sub-Index	Off-set	Access Rights	Length	Index name	Parameter	Type	Values
0x1A	0	0	R/W	32 bytes	Location tag		StringT	„*****“

11.4.16 Device Status

The simple device status can be read out with the **Device Status** parameter.

Index	Sub-Index	Off-set	Access Rights	Length	Index name	Parameter	Type	Values
0x24	0	0	RO	1 byte	Device Status		uint: 8	0
								2
								4

Description of parameter values

Index name	Parameter	Values	Description
Device Status		0	The valve is operating properly
		2	The valve is operated outside the specification
		4	The valve is in fault status

11.4.17 Detailed Device Status

The detailed device status can be read out with the **Detailed Device Status** parameter. The values of the array correspond to the IO-Link events (see chapter 12.5 Events).

Index	Sub-Index	Off-set	Access Rights	Length	Index name	Parameter	Type	Values
0x25	0	0	RO	39 byte	Detailed Device Status		ArrayT	See chapter 12.5 Events

Description of parameter values

Index name	Parameter	Values	Description
Detailed Device Status			See chapter 12.5 Events

11.4.18 Actuator size

The actuator size can be read out in numbers with the **Actuator size** parameter.

Index	Sub-Index	Offset	Access Rights	Length	Index name	Parameter	Type	Default	Values
0x40	0	0	RO	2 bits	Actuator size		uint: 8	Depending on the actuator size used	0 → size 0 1 → size 1 2 → size 2

11.4.19 Function digital inputs

The functions of the digital inputs can be configured with the **Function digital inputs** parameter.

Index	Sub-Index	Offset	Access Rights	Length	Index name	Parameter	Type	Default	Values
0x4B	1	0	R/W	3 bits	Function digital inputs	Input 1	uint:8	1	0
									1
									2
									3
									4
	2	8	R/W	3 bits		Input 2	uint:8	2	0
									1
									2
									3
									4

Description of parameter values

Index name	Parameter	Values	Description

11.4.20 Function digital in- / output 1

The function of the input/output can be set with the **Function Digital In-/Output 1** (subindex 1) parameter.

Index	Sub- In- dex	Off- set	Access Rights	Length	Index name	Parameter	Type	Default	Values
0x4C	1	0	R/W	3 bits	Function digital in- / output 1	In- / output 1	uint:8	4	0
									1
									2
									3
									4
	2	8	R/W	3 bits		Type in- / output 1	uint:8	0	0
									1
									2

Description of parameter values

Index name	Parameter	Values	Description
Function digital in- / output 1	In- / output	0	(Output Open) Signal is output with the corresponding valve position. Detection of Open depends on the setting of the parameter Position Feedback (index 0x51 (see "Actuator position feedback", page 41)) and a correct initialization.
		1	(Output Close) Signal is output with the corresponding valve position. Detection of Close depends on the setting of the parameter Position Feedback (index 0x51 (see "Actuator position feedback", page 41)) and a correct initialization.
		2	(Output Error) Only output error detection.
		3	(Output Error & Warning) Output error and warnings.
		4	(Input Init) Configure input/output as initialization input.
	Type in- / output	0	(Push-Pull) Configure output as Push-Pull.
		1	(NPN) Configure output as NPN.
		2	(PNP) Configure output as PNP.

11.4.21 Function digital output 2

The output function can be set with the **Function digital output 2** parameter.

Index	Sub-Index	Offset	Access Rights	Length	Index name	Parameter	Type	Default	Values
0x4D	0	0	R/W	2 bits	Function digital output 2		uint:8	2	0 1 2 3

Description of parameter values

Index name	Parameter	Values	Description
Function digital output		0	(Output Open) Signal is output with the corresponding valve position. Detection of Open depends on the setting of the parameter Position Feedback (index 0x51 (see "Actuator position feedback", page 41)) and a correct initialization.
		1	(Output Close) Signal is output with the corresponding valve position. Detection of Close depends on the setting of the parameter Position Feedback (index 0x51 (see "Actuator position feedback", page 41)) and a correct initialization.
		2	(Output Error) Only output error detection.
		3	(Output Error & Warning) Output error and warnings.

11.4.22 Logic digital inputs / outputs

The inputs and outputs can be inversed with the **Logic digital inputs/outputs** parameters.

Index	Sub-Index	Offset	Access Rights	Length	Index name	Parameter	Type	Default	Values
0x4E	1	0	R/W	1 bit	Logic digital inputs / outputs	Input 1	Boolean	0	0 1
	2	1	R/W	1 bit		Input 2	Boolean	0	0 1
	3	2	R/W	1 bit		Input / output 1	Boolean	0	0 1
	4	3	R/W	1 bit		Output 2	Boolean	0	0 1

Description of parameter values

Index name	Parameter	Values	Description
Logic digital inputs / outputs	Input 1	0	(Active high) Input 1 not inversed.
		1	(Active low) Input 1 inversed.
	Input 2	0	(Active high) Input 2 not inversed.
		1	(Active low) Input 2 inversed.
	Input / output 1	0	(Active high) Input/output not inversed.
		1	(Active low) Input/output inversed.
	Output 2	0	(Active high) Output not inversed.
		1	(Active low) Output inversed.

11.4.23 Error action

The safety position can be set with the **Error action** parameter.

The safety position is approached when an error occurs, if the supply voltage is too low within the range of 17.8 V to 21.1 V or in case of the corresponding signal present at Safe/On (see "Failure counter", page 42).

NOTICE

- Except the Temperature Over-Run error device, exceeding the permissible motor temperature. If the permissible temperature is exceeded, the motor is switched off to prevent damage.

Index	Sub-Index	Off-set	Access Rights	Length	Index name	Parameter	Type	Default	Values
0x4F	0	0	R/W	2 bits	Error action	Error action	uint:8	2	0 1 2

Description of parameter values

Index name	Parameter	Values	Description
Error action	Error action	0	(Hold) Actuator remains in the current position in case of an error.
		1	(Open) Actuator moves to the OPEN position in case of an error.
		2	(Close) Actuator moves to the CLOSED position in case of an error.

11.4.24 Basic settings

The different settings are summarized with the **Basic settings** parameter.

Index	Sub-Index	Off-set	Access Rights	Length	Index name	Parameter	Type	Default	Values
0x50	1	0	R/W	1 bit	Basic settings	Inversion of LED colours	Boolean	0	0
									1
	2	1	R/W	1 bit		On site initialization	Boolean	0	0
									1
	3	2	R/W	1 bit		Initialization mode	Boolean	0	0
									1
	4	3	R/W	1 bit		IO-Link process data	Boolean	0	0
									1

Description of parameter values

Index name	Parameter	Values	Description
Basic settings	Inversion of LED colours	0	(Standard) LEDs Close = green and Open = yellow (not inversed).
		1	(Inversed) LEDs Close = yellow and Open = green (inversed).
	On site initialization	0	(Enabled) On-site initialization activated.
		1	(Disabled) On-site initialization deactivated.
	Initialization mode	0	Automatic initialization mode activated.
		1	Manual initialization mode activated.
	IO-Link process data	0	(Disabled) Use of IO-Link process data (see "Process data", page 25) is deactivated.
		1	(Enabled) Use of IO-Link process data (see "Process data", page 25) is activated.

11.4.25 Actuator position feedback

The settings for the OPEN and CLOSED position feedback can be stored with the **Actuator position feedback** parameter.

Index	Sub-Index	Offset	Access Rights	Length	Index name	Parameter	Type	Default	Values
0x51	1	0	R/W	10 bits	Actuator position feedback	Open request	uint:16	900 (90.0%)	30 ... 970 (3.0 ... 97.0%)
	2	16	R/W	10 bits		Close request	uint:16	100 (10.0%)	30 ... 970 (3.0 ... 97.0%)
	3	32	RO	10 bits		Open real	uint:16		0 ... 4095
	4	48	RO	10 bits		Close real	uint:16		0 ... 4095

Description of parameter values

Index name	Parameter	Values	Description
Actuator position feedback	Open request	30 ... 970 (3.0 ... 97.0%)	Request valve position OPEN
	Close request	30 ... 970 (3.0 ... 97.0%)	Request valve position CLOSED
	Open real	0 ... 4095	Real valve position OPEN
	Close real	0 ... 4095	Real valve position CLOSED

11.4.26 Initialized positions

The analog values of the initialized valve positions can be read out with the **Initialized positions** parameter.

Index	Sub-Index	Offset	Access Rights	Length	Index name	Parameter	Type	Default	Values
0x53	1	0	RO	12 bits	Initialized positions	Open	uint:16	0	0 ... 4092
	2	16	RO	12 bits		Close	uint:16	4092	0 ... 4092
	3	32	RO	12 bits		Stroke	uint:16	0	0 ... 4092

Description of parameter values

Index name	Parameter	Values	Description
Initialized positions	Open	0 ... 4092	Analog value valve position OPEN
	Close	0 ... 4092	Analog value valve position CLOSED
	Stroke	0 ... 4092	Analog value stroke (difference between OPEN and CLOSED).

11.4.27 Calibration positions

The values of the factory calibration can be read out with the **Calibration positions** parameter.

The values are analog values of the potentiometer in the mechanical end positions of the actuator.

Index	Sub-Index	Offset	Access Rights	Length	Index name	Parameter	Type	Default	Values
0x55	1	0	RO	12 bits	Calibration positions	Max.	uint:16	0	0 ... 4092
	2	16	RO	12 bits		Min.	uint:16	4092	0 ... 4092

Description of parameter values

Index name	Parameter	Values	Description
Calibration positions	Max.	0 ... 4092	Read out analog value of the potentiometer for the mechanical end position OPEN.
	Min.	0 ... 4092	Read out analog value of the potentiometer for the mechanical end position CLOSED.

11.4.28 Cycle counter

Switching cycles of the actuator or of the valve are counted with the **Cycle counter** parameter.

For a switching cycle, end position OPEN and then end position CLOSED must be detected. This also means that cycles are not counted for a programming/initialization error.

Index	Sub-Index	Offset	Access Rights	Length	Index name	Parameter	Type	Default	Values
0x56	1	0	R/W	24 bits	Cycle counter	User	uint:24	0	0 ... 16.777.215
	2	32	RO	24 bits		Total	uint:24	0	0 ... 16.777.215

Description of parameter values

Index name	Parameter	Values	Description
Cycle counter	User	0 ... 16.777.215	Customer switching cycles (resettable)
	Total	0 ... 16.777.215	Total of switching cycles (not resettable)

11.4.29 Failure counter

For the **Failure counter** parameter, occurring errors and events are counted and emitted.

Index	Sub-Index	Offset	Access Rights	Length	Index name	Parameter	Type	Default	Values
0x57	1	0	RO	16 bits	Failure counter	Undervoltage	uint: 16	-	0 ... 65.535
	2	16	RO	16 bits		Temperature error	uint: 16	-	0 ... 65.535
	3	32	RO	16 bits		Motor unable to move	uint: 16	-	0 ... 65.535
	4	48	RO	16 bits		Internal error	uint: 16	-	0 ... 65.535
	5	64	RO	16 bits		Emergency power	uint: 16	-	0 ... 65.535
	6	80	RO	16 bits		Potifail open	uint: 16	-	0 ... 65.535
	7	96	RO	16 bits		Potifail close	uint: 16	-	0 ... 65.535
	8	112	RO	16 bits		Overcurrent out 1	uint: 16	-	0 ... 65.535
	9	128	RO	16 bits		Overcurrent out 2	uint: 16	-	0 ... 65.535

Description of parameter values

Index name	Parameter	Values	Description
Failure counter	Undervoltage	0 ... 65.535	Number of undervoltage errors (U < 17.4 V)
	Temperature error	0 ... 65.535	Number of actuator switch-offs due to excessive motor temperature
	Motor unable to move	0 ... 65.535	Number of motor errors
	Internal error	0 ... 65.535	Number of internal errors
	Emergency power	0 ... 65.535	Number of emergency power cases
	Potifail open	0 ... 65.535	Number of times the actuator has moved to its mechanical stop OPEN.
	Potifail close	0 ... 65.535	Number of times the actuator has moved to its mechanical stop CLOSED.
	Overcurrent out 1	0 ... 65.535	Number of times output 1 has switched off due to excessive output current.
	Overcurrent out 2	0 ... 65.535	Number of times output 2 has switched off due to excessive output current.

11.4.30 Analog values

Different analog values can be read out with the **Analog values** parameter.

Index	Sub-Index	Off-set	Access Rights	Length	Index name	Parameter	Type	Values
0x60	1	0	RO	12 bits	Analog values	Potentiometer	uint:16	0 ... 4095
	2	16	RO	12 bits		Supply voltage	uint:16	0 ... 4095
	3	32	RO	12 bits		Temperature	uint:16	0 ... 4095

Description of parameter values

Index name	Parameter	Values	Description
Analog values	Potentiometer	0 ... 4095	Read out current analog value of the potentiometer.
	Supply voltage	0 ... 4095	Read out current analog value of the supply voltage.
	Temperature	0 ... 4095	Read out current analog value of the temperature sensor.

11.4.31 Operating times

The current valve travel times can be read out with the **Operating times** parameter.

Index	Sub-Index	Off-set	Access Rights	Length	Index name	Parameter	Type	Default	Values
0x62	1	0	RO	8 bits	Operating times	Open	uint:8	0	0 to 255, 0 to 25.5 s
	2	8	RO	8 bits		Close	uint:8	0	0 to 255, 0 to 25.5 s

Description of parameter values

Index name	Parameter	Values	Description
Operating times	Open	0 to 255 0 to 25.5 s	Read out operating time (in tenths of seconds) from end position CLOSED to end position OPEN.
	Close	0 to 255 0 to 25.5 s	Read out operating time (in tenths of seconds) from end position OPEN to end position CLOSED.

11.4.32 Drive sets

The traverse speed and force of the actuator can be influenced with the **Drive sets** parameter when the valve is initialized.

Index	Sub-Index	Off-set	Access Rights	Length	Index name	Parameter	Type	Default	Values
0x90	1	0	R/W	2 bits	Drive sets	Speed		3	1 ... 3
	2	8	R/W	3 bits		Force		-	1 ... 6

Description of parameter values

Index name	Parameter	Values	Description
Drive sets	Speed	1 ... 3	Select the speeds for the average travel range.
	Force	1 ... 6	Set the force for the average travel range and for sealing. Preset at the factory depending on the valve type.

Speed

Actuator size	Setting parameter	Average speed in mm / s
AG0 and AG1	1 (43 %)	1.6
	2 (71 %)	2.3
	3 (100 %)	3.0

Force settings

Actuator size	Setting parameter	Force
AG0 and AG1	1	Minimum force
	6	Maximum force

11.5 Events

The following IO-Link events can be transmitted.

Event	Mode	Type	Code
Device Hardware Fault	App/Disapp	Error	0x5000
Motor Unable To Move	App/Disapp	Error	0x8CE0
Device Temperature Over-Run	App/Disapp	Warning/Error	0x4210
Emergency Power	App/Disapp	Warning	0x5100
Primary Supply Voltage Under-Run	App/Disapp	Warning/Error	0x5111
Potifail Close	App/Disapp	Warning	0x8CA5
Potifail Open	App/Disapp	Warning	0x8CA4

Event	Mode	Type	Code
Init Fail With No Stroke	App/Disapp	Warning	0x8CA6
Init Fail With Less Stroke	App/Disapp	Warning	0x8CA7
Init Fail After Potifail	App/Disapp	Warning	0x8CA8
Not Calibrated	App/Disapp	Warning	0x8CA9
Over Current Output 1	App/Disapp	Warning	0x8CC0
Over Current Output 2	App/Disapp	Warning	0x8CC1
Non Volatile Memory Loss	Single Shot	Warning	0x5011
Parameter Changed	Single Shot	Information	0x6350

Description – Events

Event	Description	Possible cause	Troubleshooting
Device Hardware Fault 0x5000	The event occurs when a hardware fault is detected.	Fault in valve position detection. Parameter can no longer be read when switching the device on.	Contact GEMÜ Support
Motor Unable To Move 0x8CE0	The event occurs when the motor is blocked.	Valve is blocked (for example, solid stuck in valve). Valve corroded (rusted in place). End position can no longer be reached (after replacing the diaphragm).	Check valve Carry out initialization if valve is OK
Device Temperature Over-Run 0x4210	The event occurs as a warning or error if the motor temperature is too high.	Control is operated outside of the specification. The ambient temperature is too high.	Check temperature Set control correctly (check duty cycle (ED) of the actuator)
Emergency Power 0x5100	The event occurs if the Safe/ On function is selected on a digital input and the enabling signal falls. For example, by triggering a fail safe function or in case of emergency power.	The connected external fail safe function triggers. Supply by an external emergency power supply module	Check the plant and search for the cause of the disconnection.
Primary Supply Voltage Under-Run 0x5111	The event occurs if the supply is too low. The event is triggered as a warning if the supply voltage U_v is below a value of 21.1 V. (If the supply voltage is below 17.4 V, the event Primary Supply Voltage Under-Run (0x5111) is triggered as an error).	Power supply unit overloaded. Cross-section of the supply line is too small. Supply line is too long.	Check supply
Potifail Close 0x8CA5	The event occurs if a valve position is read which can never be achieved in the "Close" direction.	Fault in valve position detection. Error when replacing a diaphragm (stroke of the valve in incorrect area). Actuator has been fitted on the valve incorrectly (stroke of the valve in the incorrect area).	Check valve/diaphragm

Event	Description	Possible cause	Troubleshooting
Potifail Open 0x8CA4	The event occurs if a valve position is read which can never be achieved in the "Open" direction.	Fault in valve position detection.	Check valve/diaphragm
		Error when replacing a diaphragm (stroke of the valve in incorrect area).	
		Actuator has been fitted on the valve incorrectly (stroke of the valve in the incorrect area).	
Init Fail 0x8CA6 0x8CA7 0x8CA8	The events occur if the distance between the OPEN and CLOSED positions determined during initialization is implausible.	Valve is blocked (for example, solid stuck in valve).	Check valve Carry out initialization if valve is OK
		Valve is corroded (rusted in place).	
		Valve not yet initialized.	
		Initialization carried out with incorrectly mounted valve (spindle, diaphragm or valve body incorrectly mounted, for example).	
Not Calibrated 0x8CA9	The event occurs if the actuator does not have a valid calibration. The actuator is calibrated in the factory.		Contact GEMÜ Support
Over Current Output 1 0x8CC0	The event occurs when a short circuit is present at pin 5 (digital input/digital output).	Supply line insulation is damaged.	Check supply line
		Incorrect pin configuration.	Check pin configuration
		Incorrect wiring of the pin.	Check the wiring of the pin
Over Current Output 2 0x8CC1	The event occurs when a short circuit is present at pin 6 (digital output (IO-Link)).	Supply line insulation is damaged.	Check supply line
		Incorrect wiring of the pin.	Check the wiring of the pin
Non Volatile Memory Loss 0x5011	The event occurs when it has been determined when starting the actuator that the specific data in the actuator's read-only memory has been changed unintentionally.	Save values in the read-only memory in case of power failure (eSyStep OPEN/CLOSE does not have any power buffering).	It is uncritical data in the case of this event, the actuator still functions
Parameter Changed 0x6350	The event occurs when it is has been determined when starting the actuator that the configuration data in the actuator's read-only memory has been changed unintentionally. The configuration data that has been changed has been reset to its default values. The event serves to signal the changes in the configuration data.	Save values in the read-only memory in case of power failure (eSyStep OPEN/CLOSE does not have any power buffering).	Check the configuration of the actuator

12 Operation

12.1 Initialization

Initialization must be carried out in the following situations:

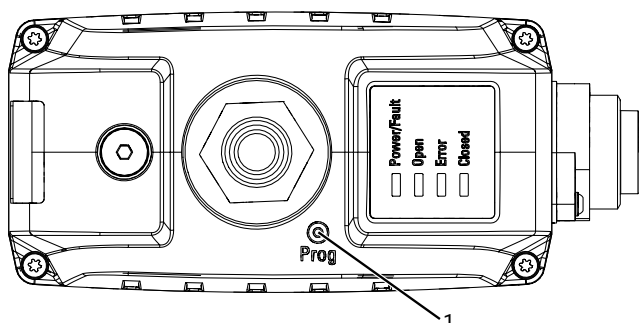
- Tube replacement
- Tube holder replacement
- Compressor replacement

If the process valve is fully assembled at the factory, initialization has already been carried out.

Initialization can be carried out using the following procedures:

- On-site initialization
- Initialization via IO-Link
- Initialization via configurable digital input (digital input must be set to "Init")

12.1.1 On-site initialization of the end positions



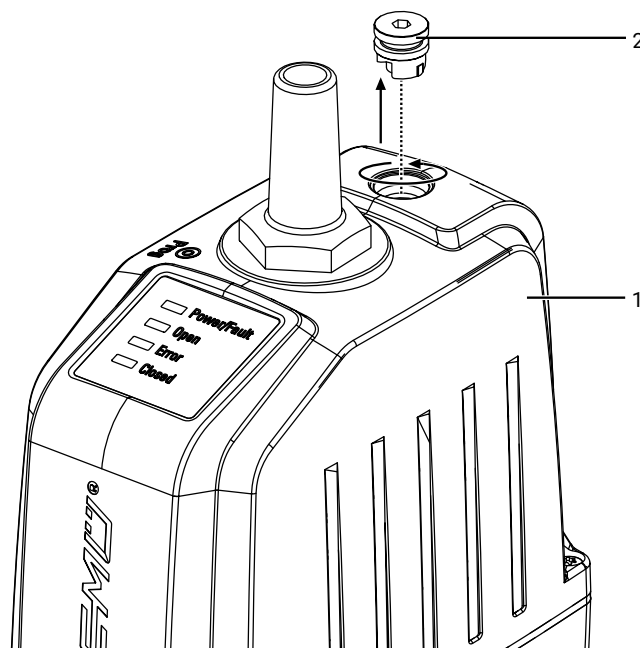
1. Connect supply voltage.
2. Hold the magnet briefly (>100 ms) at the point on the housing cover marked with PROG 1.
 - ⇒ OPEN and CLOSED LEDs flash alternately.
3. Valve automatically moves into the OPEN position.
4. Valve automatically moves into the CLOSED position.
5. Initialization mode is automatically ended.
6. The end positions are set.

12.1.2 Initialization of the end positions via IO-Link

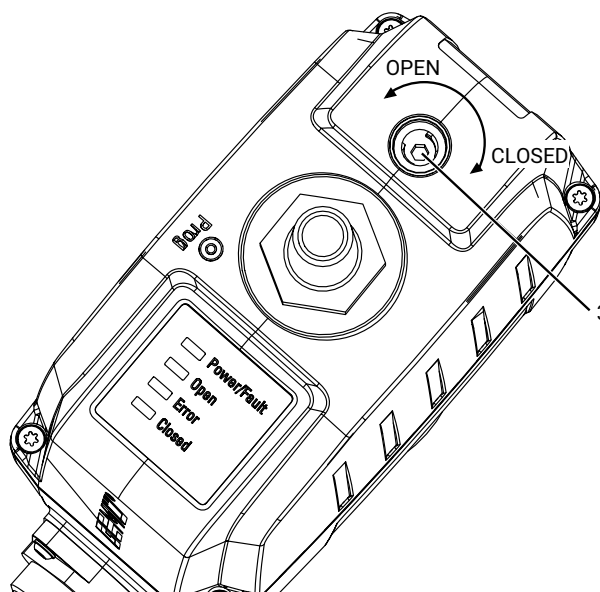
1. Select automatic initialization mode (parameter data "Initialization Mode").
2. Briefly activate (>100 ms) initialization mode (process data "Selection of operating mode").
 - ⇒ OPEN and CLOSED LEDs flash alternately.
3. Valve automatically moves into the OPEN position.
4. Valve automatically moves into the CLOSED position.
5. Initialization mode is automatically ended.
6. The end positions are set.

12.2 Manual override

Open, actuate and close the manual override with the hexagon socket (SW3).



1. Unscrew sealing plug 2 anti-clockwise out of cover 1 and remove it.



2. Operate the manual override 3 with the hexagon socket (WAF3).
 - ⇒ Turn clockwise to close the valve.
 - ⇒ Turn anticlockwise to open the valve.

13 Inspection and maintenance

⚠ WARNING



The equipment is subject to pressure!

- ▶ Risk of severe injury or death
- Depressurize the plant or plant component.
- Completely drain the plant or plant component.

NOTICE

Use of incorrect spare parts!

- ▶ Damage to the GEMÜ product
- ▶ The manufacturer liability and guarantee will be void.
- Use only genuine parts from GEMÜ.

⚠ CAUTION



Hot plant components!

- ▶ Burns
- Only work on plant that has cooled down.
- Wear protective gear.

⚠ CAUTION



Risk of crushing!

- ▶ Risk of severe injury
- Before performing any work on the GEMÜ product, depressurize the plant.

NOTICE

Requirements for tube lines used!

- ▶ Use tube lines suitable for the application, see manufacturer's information.
- Only use undamaged tube lines.

NOTICE

Lay tube lines professionally!

- ▶ Lay tube lines professionally and do not bend them below the minimum bending radius, see manufacturer's information.
- Do not kink or twist the tube lines.

NOTICE

Exceptional maintenance work!

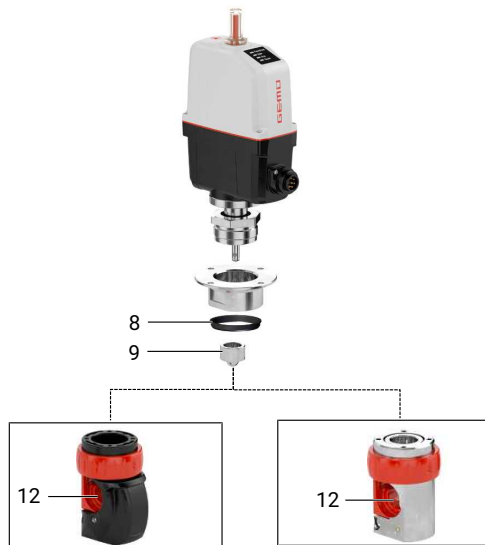
- ▶ Damage to the GEMÜ product
- Any maintenance work and repairs not described in these operating instructions must not be performed without consulting the manufacturer first.

The operator must carry out regular visual examination of the GEMÜ products dependent on the operating conditions and the potential danger in order to prevent leakage and damage.

The product also must be disassembled and checked for wear in the corresponding intervals.

1. Have servicing and maintenance work performed by trained personnel.
2. Wear appropriate protective gear as specified in plant operator's guidelines.
3. Shut off plant or plant component.
4. Secure the plant or plant component against recommissioning.
5. Depressurize the plant or plant component.
6. Actuate GEMÜ products which are always in the same position four times a year.
7. If necessary, the end position counter **User** can be reset after maintenance or other changes under parameter Cycle Counter.

13.1 Spare parts



Item	Name	Item number	Designation
8	Gasket	88855875	Q00 BG0 DR
		88855876	Q00 BG1 DR
		88855876	Q00 BG2 DR
9	Compressor	88949093	Q00 2DA BG0 DS
		88949096	Q00 2DC BG0 DS
		88982244	Q00 3DC BG0 DS
		88982247	Q00 3DD BG0 DS
		88949097	Q00 4DC BG0 DS
		89012886	Q00 4DC BG1 DS
		88949098	Q00 4DD BG0 DS
		89012887	Q00 4DD BG1 DS
		88949099	Q00 4DE BG0 DS
		89012888	Q00 4DE BG1 DS
		88941603	Q00 5DD BG0 DS
		88982248	Q00 5DE BG0 DS
		88982249	Q00 6DF BG1 DS
		88949100	Q00 6DG BG1 DS
		88949101	Q00 8DH BG1 DS

Item	Name	Item number	Designation
9, 12	Compressor, tube holder	89012889	Q00 8DH BG2 DS
		88949102	Q00 8DI BG1 DS
		89012891	Q00 8DI BG2 DS
		88949103	Q00 12DK BG2 DS
		88949104	Q00 16DN BG2 DS
		89011608	Q00 2DA77 BG0 SD
		89011609	Q00 2DC77 BG0 SD
		89011635	Q00 3DC77 BG0 SD
		89011638	Q00 3DD77 BG0 SD
		89011610	Q00 4DC77 BG0 SD
		88985967	Q00 4DC77 BG1 SD
		89011612	Q00 4DD77 BG0 SD
		88986001	Q00 4DD77 BG1 SD
		89003439	Q00 4DE77 BG0 SD
		88986009	Q00 4DE77 BG1 SD
		89011638	Q00 5DD77 BG0 SD
		89011639	Q00 5DE77 BG0 SD
		89011640	Q00 6DF77 BG1 SD
		89011613	Q00 6DG77 BG1 SD
		89011614	Q00 8DH77 BG1 SD
		88986010	Q00 8DH77 BG2 SD
		89003438	Q00 8DI77 BG1 SD
		88986011	Q00 8DI77 BG2 SD
		89011615	Q00 12DK77 BG2 SD
		89011616	Q00 16DN77 BG2 SD

Item	Name	Item number	Designation
		88855849	Q00 2DA7P BG0 SD
		88855851	Q00 2DC7P BG0 SD
		88982185	Q00 3DC7P BG0 SD
		88982187	Q00 3DD7P BG0 SD
		88855852	Q00 4DC7P BG0 SD
		88855853	Q00 4DD7P BG0 SD
		88855854	Q00 4DE7P BG0 SD
		88982188	Q00 5DD7P BG0 SD
		88982189	Q00 5DE7P BG0 SD
		88982190	Q00 6DF7P BG1 SD
		88855855	Q00 6DG7P BG1 SD
		88855856	Q00 8DH7P BG1 SD
		88855857	Q00 8DI7P BG1 SD
		88855858	Q00 12DK7P BG2 SD
		88855859	Q00 16DN7P BG2 SD
12	Tube holder	89011618	Q00 2DA77 BG0 SA
		89011619	Q00 2DC77 BG0 SA
		89011641	Q00 3DC77 BG0 SA
		89011642	Q00 3DD77 BG0 SA
		89011620	Q00 4DC77 BG0 SA
		89012900	Q00 4DC77 BG1 SA
		89011623	Q00 4DD77 BG0 SA
		89012901	Q00 4DD77BG1 SA
		89009659	Q00 4DE77 BG0 SA
		89012902	Q00 4DE77 BG1 SA

Item	Name	Item number	Designation
		89011643	Q00 5DD77 BG0 SA
		89011644	Q00 5DE77 BG0 SA
		89011645	Q00 6DF77 BG1 SA
		89011625	Q00 6DG77 BG1 SA
		89011626	Q00 8DH77 BG1 SA
		89011626	Q00 8DH77 BG2 SA
		89011628	Q00 8DI77 BG1 SA
		89012907	Q00 8DI77 BG2 SA
		89011629	Q0012DK77 BG2 SA
		89011630	Q0016DN77 BG2 SA
		88909868	Q00 2DA7P BG0 SA
		88909869	Q00 2DC7P BG0 SA
		88982259	Q00 3DC7P BG0 SA
		88982261	Q00 3DD7P BG0 SA
		88909870	Q00 4DC7P BG0 SA
		88909871	Q00 4DD7P BG0 SA
		88909872	Q00 4DE7P BG0 SA
		88982268	Q00 5DD7P BG0 SA
		88982269	Q00 5DE7P BG0 SA
		88982270	Q00 6DF7P BG1 SA
		88909873	Q00 6DG7P BG1 SA
		88909880	Q00 8DH7P BG1 SA
		88909882	Q00 8DI7P BG1 SA
		88909883	Q00 12DK7P BG2 SA
		88909884	Q00 16DN7P BG2 SA

13.2 Removing the tube

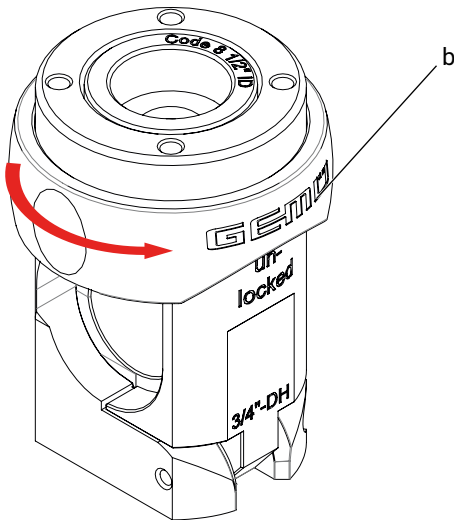
⚠ CAUTION



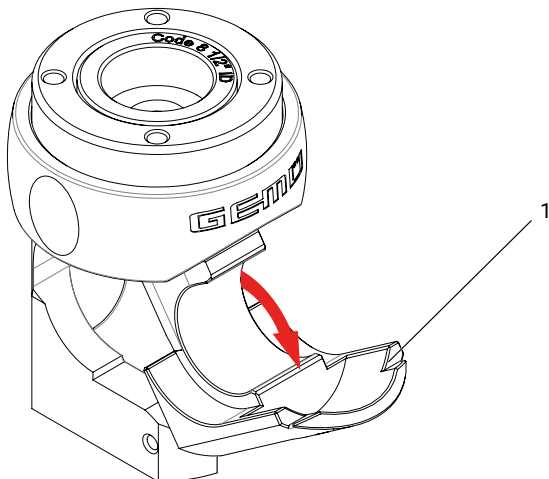
Risk of crushing!

- ▶ While the tube holder is open, the actuator can move. Severe injury due to crushing or shearing of the fingers.
- Ensure that the actuator remains in the open position during tube replacement.
- Do not reach into the tube crushing area.

1. Move actuator **A** to the open position (Total Open for tube replacement function A order code).



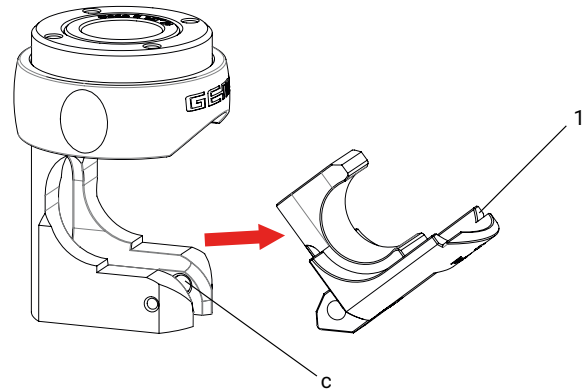
2. Turn the locking ring **b** by 90° in the direction of the arrow.
⇒ The word "unlocked" can be read on the tube holder.



3. Open the tube holder **1**.
4. Remove the tube.

13.3 Disassembling the tube holder

1. Remove the tube.



2. Loosen the fixing screw **c** using an Allen key.
3. Remove the tube holder **1**.

13.4 Disassembling the compressor

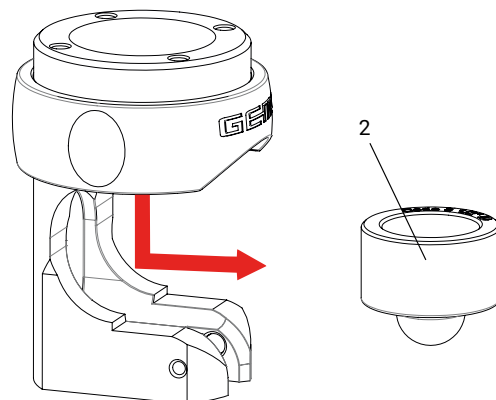
⚠ CAUTION



Risk of crushing due to the compressor shutting down!

- ▶ Severe injury due to crushing or shearing of the fingers.
- Ensure that the actuator remains in the open position while replacing the compressor.
- Do not reach into the tube crushing area.

1. Remove the tube.
2. Disassemble the tube holder (see "Disassembling the tube holder", page 51).
3. Move the actuator **A** to the closed position.

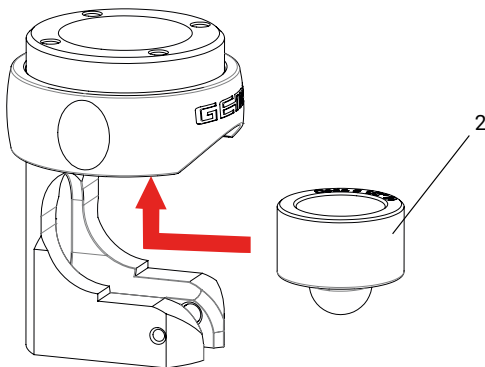


4. Pull the compressor **2** out downwards.

13.5 Installing the compressor

⚠ CAUTION	
	Risk of crushing due to the compressor shutting down! ▶ Severe injury due to crushing or shearing of the fingers. ● Ensure that the actuator remains in the open position while replacing the compressor. ● Do not reach into the tube crushing area.

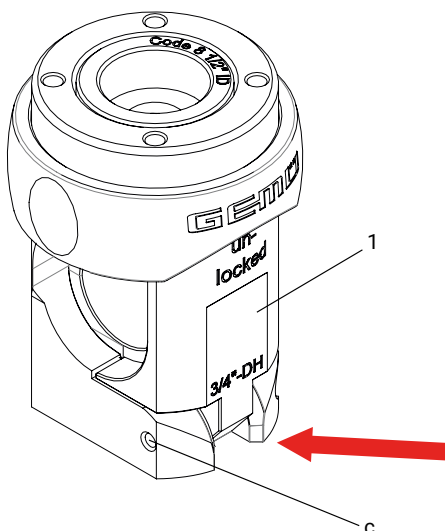
1. Remove the tube.
2. Disassemble the tube holder (see "Disassembling the tube holder", page 51).
3. Disassemble the compressor (see "Disassembling the compressor", page 51).



4. Insert the compressor **2** and press upwards until the compressor engages.
5. Move the actuator **A** to the open position.

13.6 Assembling the tube holder

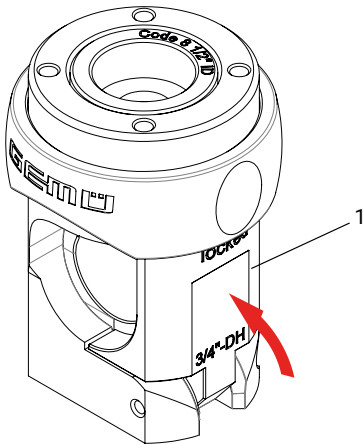
1. Disassemble the tube holder (see "Disassembling the tube holder", page 51).



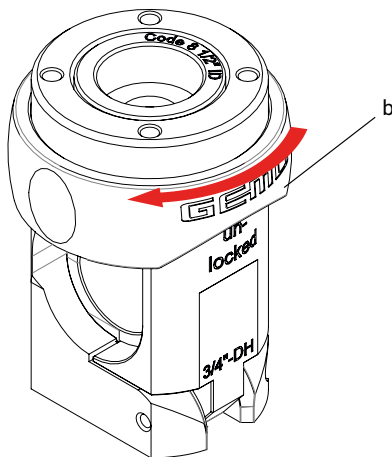
2. Insert the tube holder **1**.
3. Tighten the fixing screw **c** using an Allen key.

13.7 Inserting the tube

1. Remove the tube.
2. Insert the tube.



3. Close the tube holder 1.



4. Turn the locking ring **b** by 90° in the direction of the arrow.
⇒ The word "locked" can be read on the tube holder.
5. With the valve fully assembled, check the function and tightness.

14 Troubleshooting

14.1 LED error message

Function	Power/fault	Open	Error	Closed
Supply voltage too low				
	red			
Software Update				
Internal error				
Product not calibrated				
Motor does not move				
Product not initialized				
		Open and Closed flash alternately		
Temperature error				
Emergency power operation, OPEN position				
	red			
Emergency power operation, CLOSED position				
	red			
Emergency power operation, position unknown				
	red			
Mechanical stop, OPEN position				
Mechanical stop, CLOSED position				
Abort IO-Link communication				
Maintenance required, OPEN position				
Maintenance required, CLOSED position				
Maintenance required, position unknown				

14.2 Troubleshooting

Error	Possible cause	Troubleshooting
The product is leaking downstream (does not close or does not close fully)	Operating pressure too high	Operate the product with operating pressure specified in datasheet
	Tube leaking or damaged	Check tube for potential damage, replace tube if necessary
The product does not open or does not open fully	Actuator defective	Replace valve
	Foreign matter in the product	Remove and clean the product
	The actuator design is not suitable for the operating conditions	Use an actuator that is designed for the operating conditions
	Voltage is not connected	Connect voltage
	Cable ends incorrectly wired	Wire cable ends correctly
The product does not close or does not close fully	The actuator design is not suitable for the operating conditions	Use an actuator that is designed for the operating conditions
	Foreign matter in the product	Remove and clean the product
	Voltage is not connected	Connect voltage
The tube is damaged	The tube is slipping out of the tube holder	Route the tube such that it is centred and fully in the tube holder; if necessary, use external tube holders to position the tube upstream or downstream of the valve

15 Removal

1. Remove in reverse order to installation.
2. Unscrew the electrical wiring.
3. Disassemble the product. Observe warning notes and safety information.

16 Disposal

- The product must not be disposed of. The product must be returned to GEMÜ, see form "Agreement on the provision of field test samples".

17 Returns

Legal regulations for the protection of the environment and personnel require that the completed and signed return delivery note is included with the dispatch documents. Returned goods can be processed only when this note is completed. If no return delivery note is included with the product, GEMÜ cannot process credits or repair work but will dispose of the goods at the operator's expense.

1. Clean the product.
2. Request a return delivery note from GEMÜ.
3. Complete the return delivery note.
4. Send the product with a completed return delivery note to GEMÜ.

18 EU Declaration of Incorporation according to the EC Machinery Directive 2006/42/EC, Annex II B



EU Declaration of Incorporation

according to the EC Machinery Directive 2006/42/EC, Annex II B

We, the company

GEMÜ Gebr. Müller Apparatebau GmbH & Co. KG
Fritz-Müller-Strasse 6–8
74653 Ingelfingen
Germany

hereby declare under our sole responsibility that the below-mentioned product complies with the relevant essential health and safety requirements in accordance with Annex I of the above-mentioned Directive.

Product: GEMÜ Q50
Product name: Motorized pinch valve
The following essential health and safety requirements of the EC Machinery Directive 2006/42/EC, Annex I have been applied or adhered to: 1.1.5.; 1.2.1.; 1.2.2.; 1.2.3.; 1.2.5.; 1.3.; 1.3.2.; 1.3.4.; 1.3.7.; 1.3.8.; 1.3.9.; 1.5.14.; 1.5.3.; 1.5.5.; 1.6.1.; 1.6.3.
The following harmonized standards (or parts thereof) have been applied: EN ISO 12100:2010

We also declare that the specific technical documents have been created in accordance with part B of Annex VII.

The manufacturer undertakes to transmit relevant technical documents on the partly completed machinery to the national authorities in response to a reasoned request. This communication takes place electronically.

This does not affect the industrial property rights.

The partly completed machinery may be commissioned only if it has been determined, if necessary, that the machinery into which the partly completed machinery is to be installed meets the provisions of the Machinery Directive 2006/42/EC.

M. Barghoorn
Head of Global Technics
Ingelfingen, 18/07/2024

19 EU Declaration of Conformity in accordance with 2014/30/EU (EMC Directive)



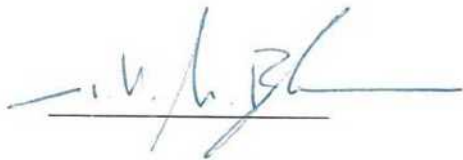
EU Declaration of Conformity

in accordance with 2014/30/EU (EMC Directive)

We, the company
GEMÜ Gebr. Müller Apparatebau GmbH & Co. KG
Fritz-Müller-Strasse 6-8
74653 Ingelfingen-Criesbach, Germany

hereby declare under our sole responsibility that the below-mentioned product complies with the regulations of the above-mentioned Directive.

Product: GEMÜ Q50
Product name: Motorized pinch valve
The following harmonized standards (or parts thereof) have been applied: EN 61000-6-4:2007/A1:2011
EN IEC 61000-6-2:2019
EN IEC 61000-6-4:2019
EN IEC 61000-6-3:2021
EN IEC 61800-3:2019



M. Barghoorn
Head of Global Technics
Ingelfingen, 18/07/2024

